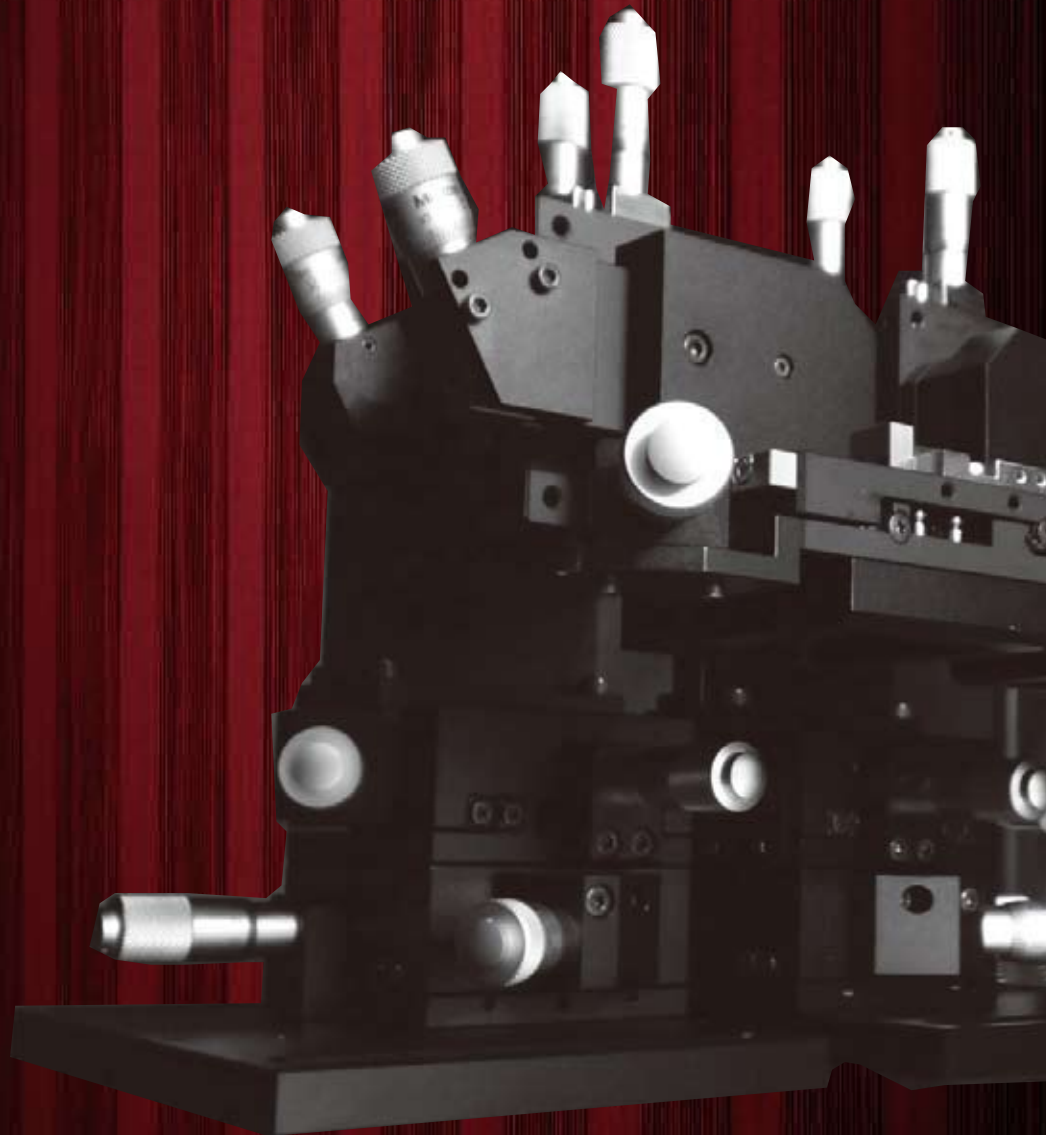
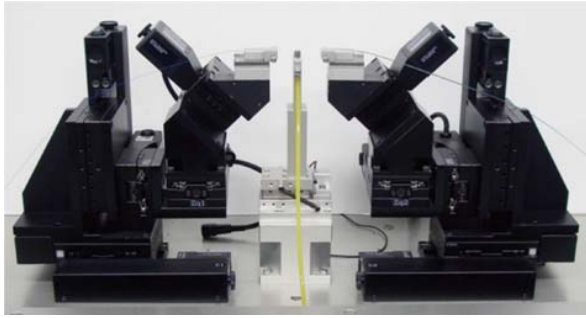


Alignment Systems



Guidance



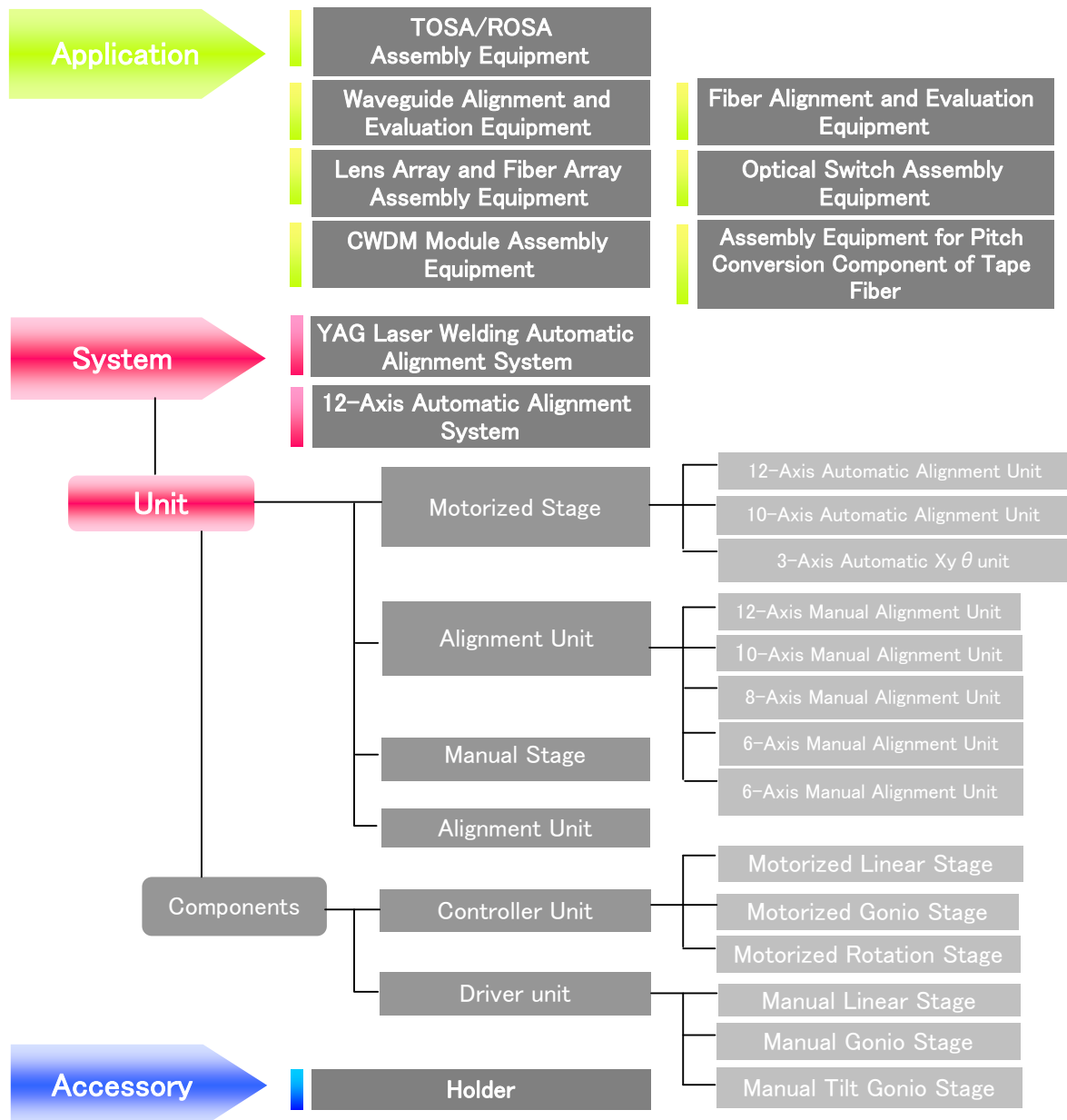
■ By combination of high accuracy manual and motorized stages and the software with our dedicated design, we can propose the optimal alignment system to meet customer's requests.

■ We can also provide not only as a single device but also one unit, and even for parts.

■ By taking advantage of the accumulated know-how for many years as an optical equipment manufacturer, we can respond to a wide range of the needs from production equipment to experiment applications. In addition, we can propose the valuable solution to suitable our customer's projects.

■ Maintenance and repair are easy because many parts for the system are selected and used from our standard of our lineup.

Configuration



YAG Laser Welding Automatic

Alignment System

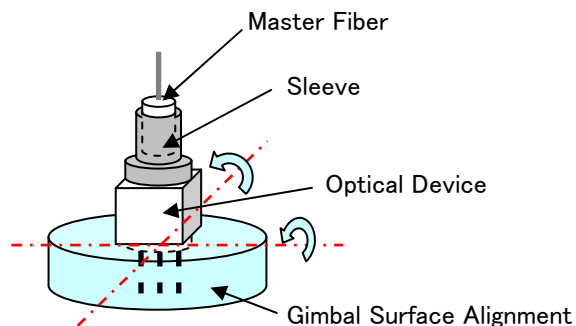
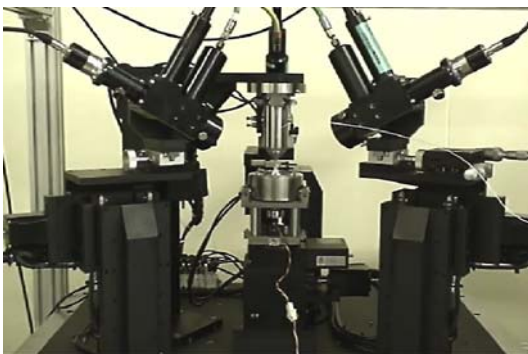
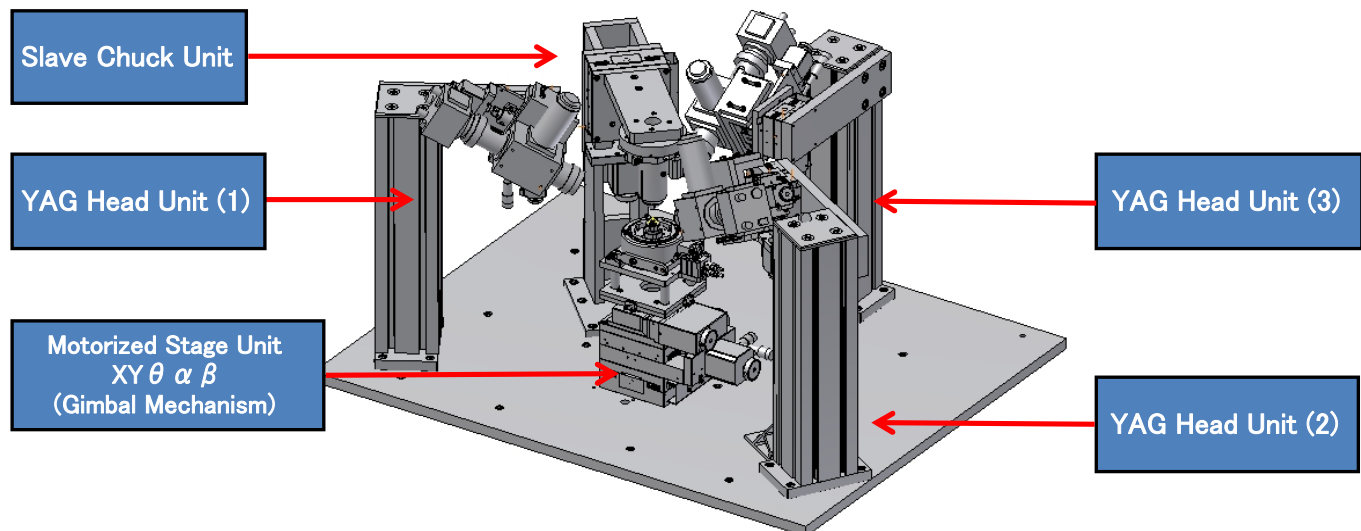
TOSA / ROSA / BOSA Assembly

- Assembly (Alignment) equipment of the active device.
- Focused on the reliability and cost performance.
- Each device holder has high reproducibility and it is easy for the attachment and detachment of the device.
- By replacing each device holder, it is available for the device of the multi-product.
- Each device holder comes with two types. (Other holder will be quoted separately.)
- Customers can create freely the most efficient algorithm to match each device.
- By adoption of gimbaled surface alignment mechanism, the device assembly time is greatly able to be reduced.
- The operation switch for remote control of various devices is prepared.
- By combination with a special optical system, since it is available for a ultra-high-speed alignment version, please contact



DAS-01AA

Configuration Example



※ The reference value does not include power meter, reference light source, LD controller, observation system unit, YAG laser or UV light source.

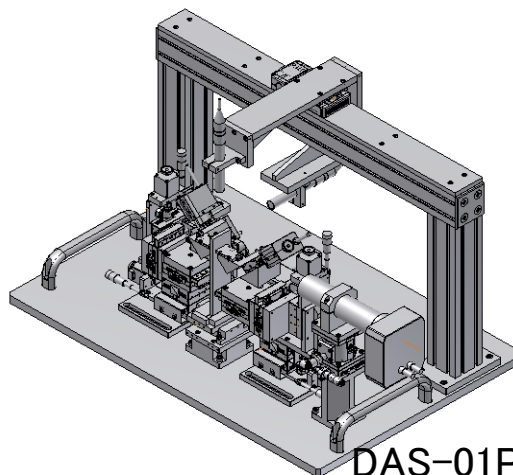
※ The separated expenses are required for shipping, installation, operation training and commissioning.

12-Axis Automatic Alignment System

Configuration Guide

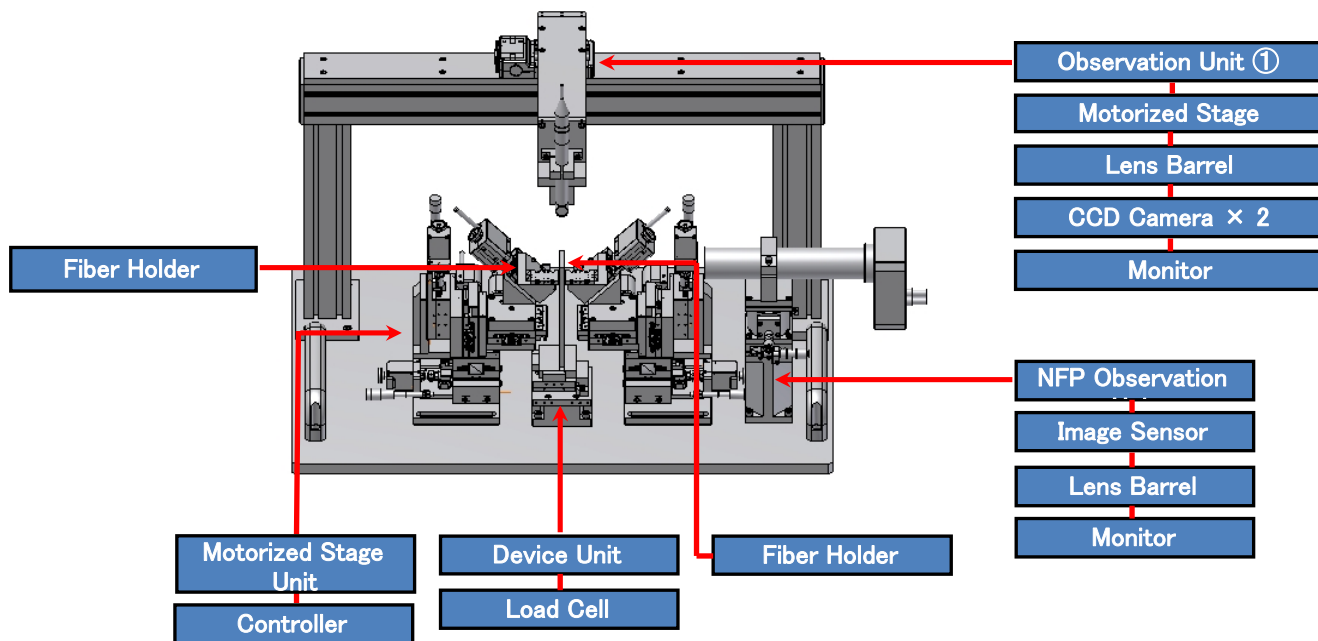
Waveguide (AWG / PLC) Alignment Equipment

- Assembly (Alignment) equipment of the passive device.
- Focused on the reliability and cost performance.
- Each 6-axis unit is arranged on the incident side and outgoing side of the waveguide device, it will do automatic alignment of a variety of devices, evaluation, assembly, etc..
- Equipped with a touch-sensitive mechanism in the central device holder station, then, it can control the gap management between the devices and the coating thickness of the UV-curable resin.
- Also possible for the alignment by the single core fiber array or by single core fiber to fiber, etc.
- Each device holder can be fixed with magnet, and such fixing type can show a good reproducibility and is easy for attachment and detachment. In addition, the assembly cycle is also be shortened because it has adopted a pre-set method.



DAS-01PA

Configuration Example



| | P/N |
|----------------------|------------|
| Motorized Stage Unit | DAU-080A-0 |
| Observation Unit ① | |
| NFP Observation Unit | |
| Device Unit | |
| Multi-Controller | SMC-16A |
| Driver Box | SMD-16 |
| Base + Frame | |

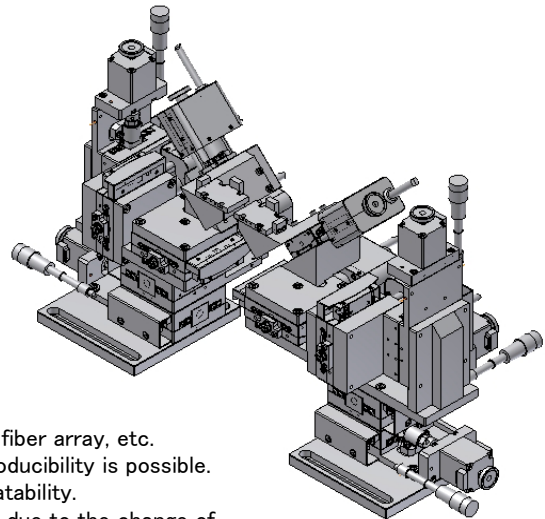
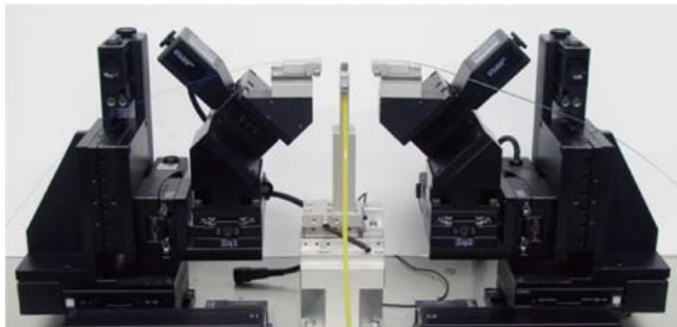
| | P/N |
|-------------|-------------|
| Stage Cable | DMINIH-CA-3 |
| GPB Cable | GP-IB-3 |

※ 1 The reference price does not include measuring instrument, vibration isolation table, light source, holder, etc. Please contact us for more information.

※ 2 Separated expenses are required for shipping, installation, operation training and commissioning.

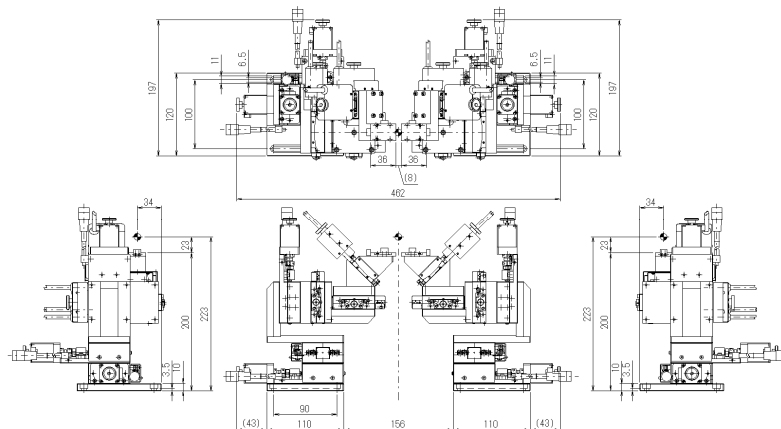
12-Axis (6-axis) Automatic Alignment Unit

DAU-080A-0/-L/-R



- 12-axis motorized stage unit with 6-axis symmetric automatic-alignment.
- Ideal for passive device alignment such as fiber array – optical waveguide – fiber array, etc.
- With high rigidity and high-performance stage, alignment with excellent reproducibility is possible.
- By fixed magnet system of the holder, available to secure the position repeatability.
- By replacing the compatible holder, possible for the extension of application due to the change of device.
(Fiber holder, fiber rotation holder, the fiber array holder, etc.)

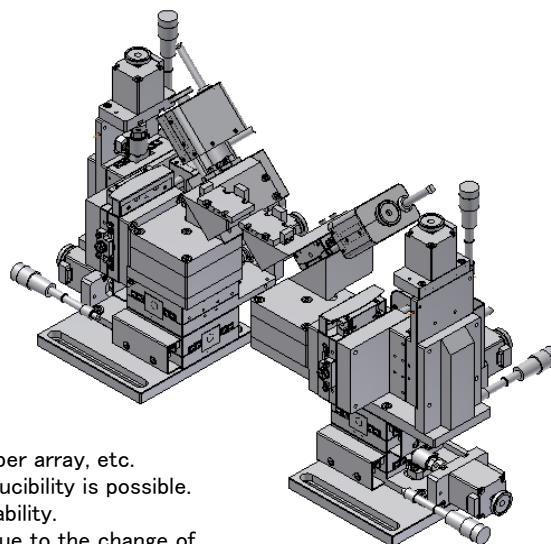
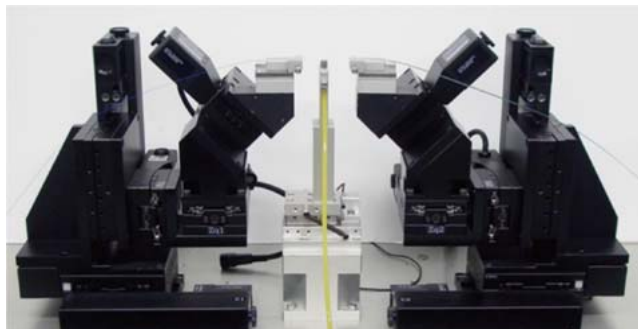
| SPEC | | | | | | | | |
|------------|----------------------|--------|--------------|------------|------------|-----------------------|-----------------------|---------------------|
| P/N | Axis | | X | Y | Z | θ_x | θ_y | θ_z |
| | P/N | | TSM60-30X/XR | | | GOHT -60A85/R | GOHT -60A105/R | GOHT -40A60/R |
| DAU-080A-L | Travel | | 30mm | 30mm | 30mm | $\pm 9^\circ$ | $\pm 7^\circ$ | $\pm 5^\circ$ |
| | Resolution | (Full) | 2 μ m | 2 μ m | 2 μ m | $\cong 0.00229^\circ$ | $\cong 0.00198^\circ$ | $\cong 0.0217$ |
| | | (Half) | 1 μ m | 1 μ m | 1 μ m | $\cong 0.00115^\circ$ | $\cong 0.00095^\circ$ | $\cong 0.0108$ |
| | Positioning Accuracy | | <6 μ m | <6 μ m | <6 μ m | — | — | — |
| | Positioning Accuracy | | <1 μ m | <1 μ m | <1 μ m | < $\pm 0.004^\circ$ | < $\pm 0.004^\circ$ | < $\pm 0.004^\circ$ |
| DAU-080A-R | Travel | | 10mm | 10mm | 10mm | $\pm 9^\circ$ | $\pm 7^\circ$ | $\pm 5^\circ$ |
| | Resolution | (Full) | 2 μ m | 2 μ m | 2 μ m | $\cong 0.00229^\circ$ | $\cong 0.00198^\circ$ | $\cong 0.0217$ |
| | | (Half) | 1 μ m | 1 μ m | 1 μ m | $\cong 0.00115^\circ$ | $\cong 0.00095^\circ$ | $\cong 0.0108$ |
| | Positioning Accuracy | | <6 μ m | <6 μ m | <6 μ m | — | — | — |
| | Positioning Accuracy | | <1 μ m | <1 μ m | <1 μ m | < $\pm 0.004^\circ$ | < $\pm 0.004^\circ$ | < $\pm 0.004^\circ$ |



| Number of Axis | P/N |
|----------------|------------|
| 12-Axis | DAU-080A-0 |
| 6-Axis | DAU-080A-L |
| 6-Axis | DAU-080A-R |

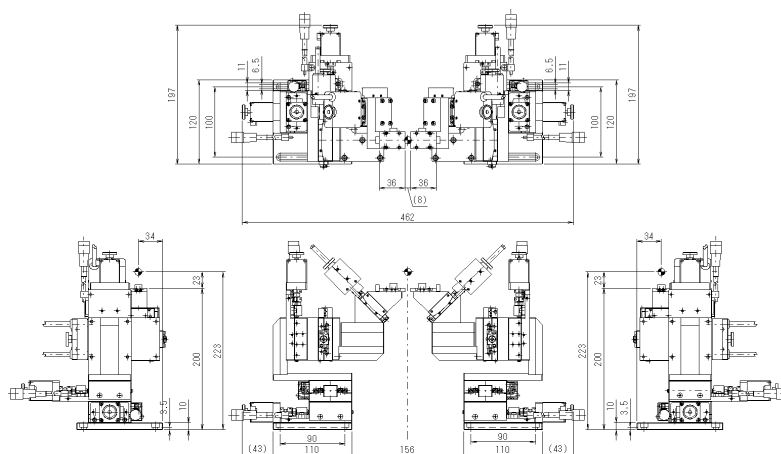
10-Axis (5-axis) Automatic Alignment Unit

DAU-070A-0/-L/-R



- 10-axis motorized stage unit with 5-axis symmetric automatic-alignment.
- Ideal for passive device alignment such as fiber array – optical waveguide – fiber array, etc.
- With high rigidity and high-performance stage, alignment with excellent reproducibility is possible.
- By fixed magnet system of the holder, available to secure the position repeatability.
- By replacing the compatible holder, possible for the extension of application due to the change of device.

| SPEC | | | | | | |
|------------|----------------------|--------------|-------------|-------------|---------------------|---------------------|
| P/N | Axis | X | Y | Z | θ_x | θ_y |
| | P/N | TSM60-30X/XR | | | GOHT -60A85/R | GOHT -60A105/R |
| DAU-080A-L | Travel | 30mm | 30mm | 30mm | $\pm 9^\circ$ | $\pm 7^\circ$ |
| | Resolution | (Full) | $2 \mu m$ | $2 \mu m$ | $\pm 0.00229^\circ$ | $\pm 0.00198^\circ$ |
| | | (Half) | $1 \mu m$ | $1 \mu m$ | $\pm 0.00115^\circ$ | $\pm 0.00095^\circ$ |
| | Positioning Accuracy | $< 6 \mu m$ | $< 6 \mu m$ | $< 6 \mu m$ | — | — |
| | Positioning Accuracy | $< 1 \mu m$ | $< 1 \mu m$ | $< 1 \mu m$ | $< \pm 0.004^\circ$ | $< \pm 0.004^\circ$ |
| DAU-080A-R | Travel | 10mm | 10mm | 10mm | $\pm 9^\circ$ | $\pm 7^\circ$ |
| | Resolution | (Full) | $2 \mu m$ | $2 \mu m$ | $\pm 0.00229^\circ$ | $\pm 0.00198^\circ$ |
| | | (Half) | $1 \mu m$ | $1 \mu m$ | $\pm 0.00115^\circ$ | $\pm 0.00095^\circ$ |
| | Positioning Accuracy | $< 6 \mu m$ | $< 6 \mu m$ | $< 6 \mu m$ | — | — |
| | Positioning Accuracy | $< 1 \mu m$ | $< 1 \mu m$ | $< 1 \mu m$ | $< \pm 0.004^\circ$ | $< \pm 0.004^\circ$ |



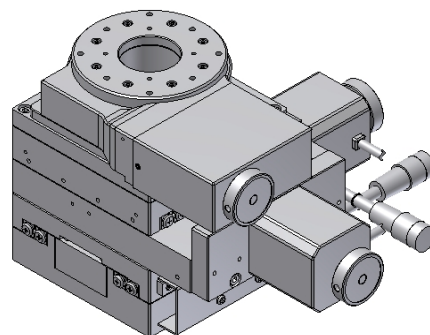
| Number of Axis | P/N |
|----------------|------------|
| 10-Axis | DAU-070A-0 |
| 5-Axis | DAU-070A-L |
| 5-Axis | DAU-070A-R |

3-Axis Automatic XY θ Unit

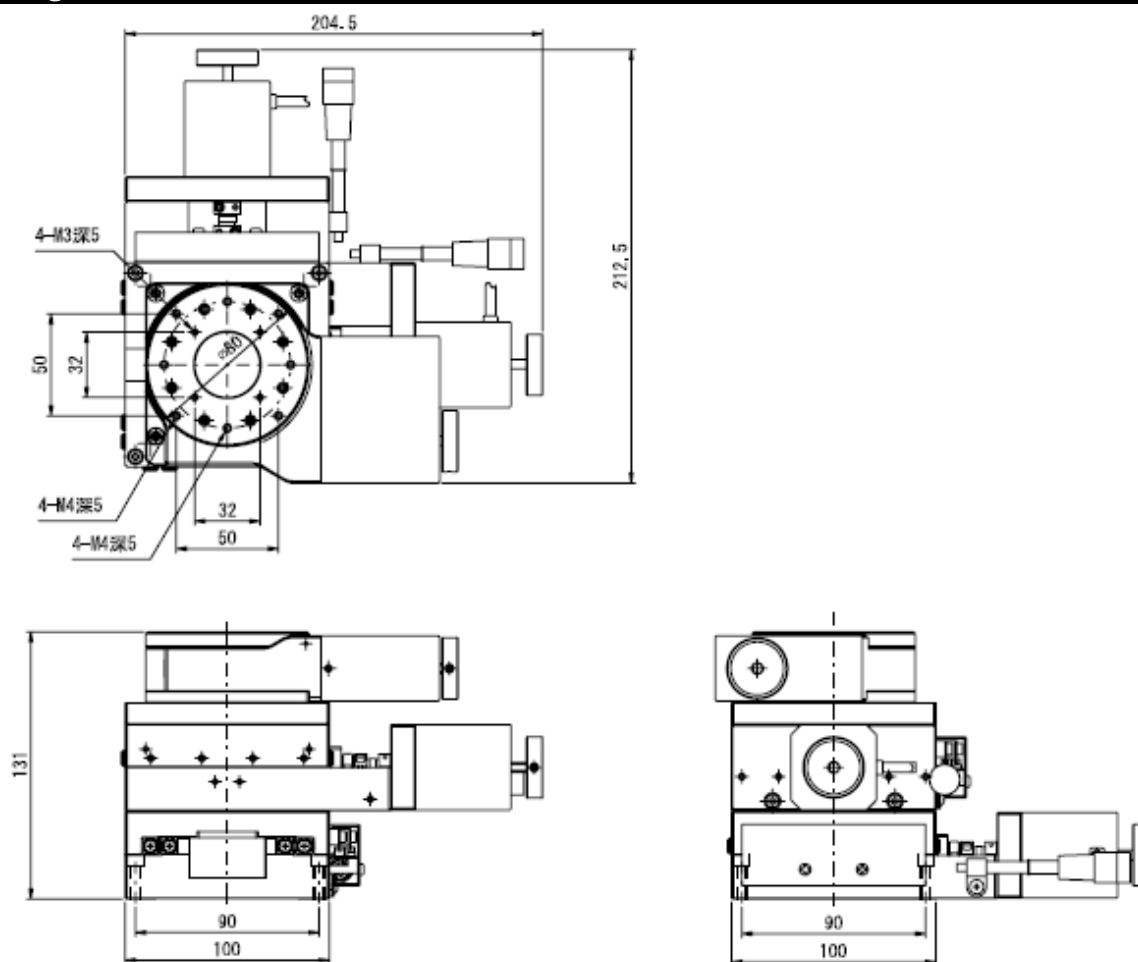
TAMM100-50X/R

SGSP-80YAW

- 3-axis automatic stage unit of XY θ required for the alignment of TOSA (UV bonded type) / ROSA, etc.
- Can be mounted YAG welding surface alignment mechanism (gimbal) unit.
- Effective to use in combination with the Z-axis.
- With high rigidity and high-performance stage, alignment with excellent reproducibility is possible.
- By fixed magnet system of the holder, available to secure the position repeatability.
- By replacing the compatible holder, possible for the extension of application due to the change of device.
(Fiber holder, fiber rotation holder, the fiber array holder, etc.)



Outline Drawing



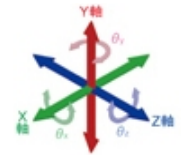
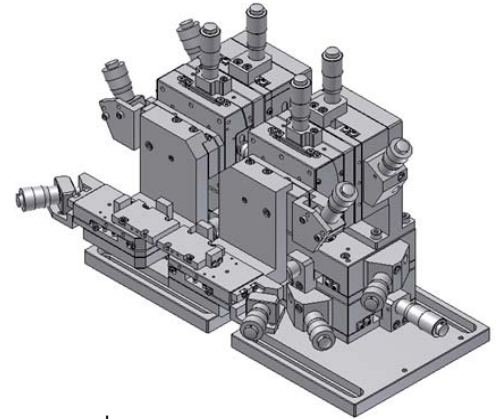
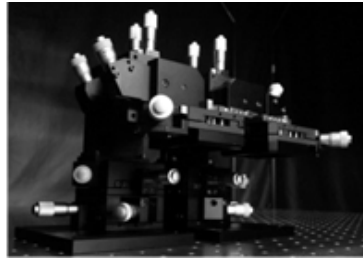
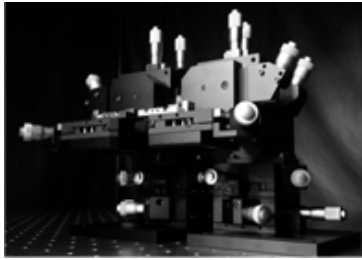
| Axis | P/N |
|----------|--------------|
| X | TAMM100-50XR |
| Y | TAMM100-50X |
| θ | SGSP-80YAW |

Total Reference Price

12-Axis (6-axis)

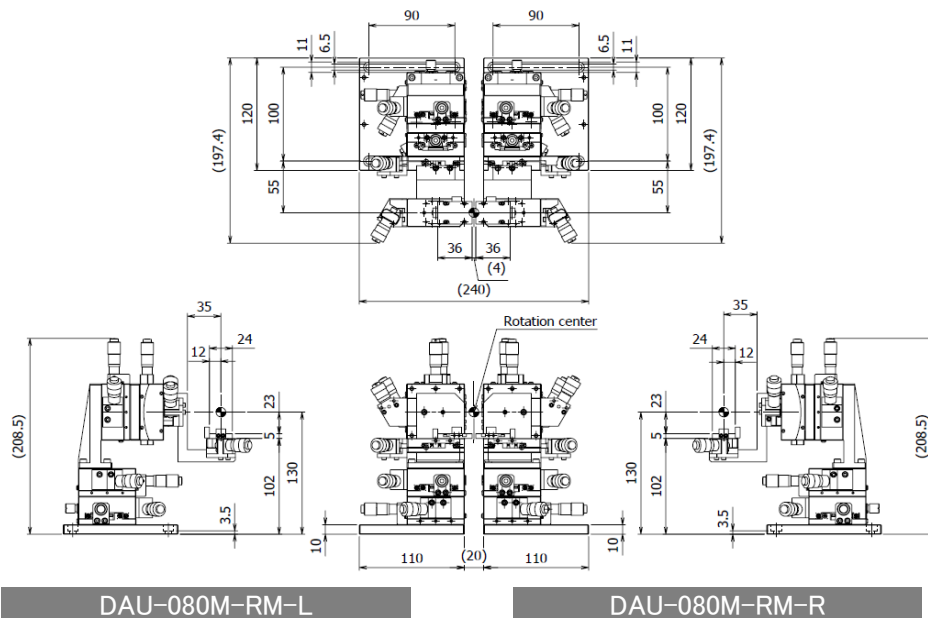
Manual Alignment Unit

DAU-080M-0/-L/-R



- 12-axis (6-axis) manual fiber alignment unit.
- Ideal for passive device alignment such as fiber array – optical waveguide – fiber array, etc.
- With high resolution stage, alignment with excellent reproducibility is possible.
- By fixed magnet system of the holder, available to secure the position repeatability.
- By replacing the compatible holder, possible for the extension of application due to the change of device.

| SPEC | | | | | | | |
|------------|------------|---|---|---|---------------------------|-----------------|----------------------|
| P/N | Axis | X | Y | Z | θ_x | θ_y | θ_z |
| | P/N | TAMF-601/R | | | GOHT-36A10 S/SR/SZ/SRZ | | GOHT-60A60 BC/BCR |
| DAU-080M-L | Travel | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | $\pm 2.5^\circ$ | $\pm 2.5^\circ$ | $\pm 5^\circ$ |
| | Resolution | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | 27.8" | 27.8" | 26.8" |
| DAU-080M-R | Travel | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | $\pm 2.5^\circ$ | $\pm 2.5^\circ$ | $\pm 5^\circ$ |
| | Resolution | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | 27.8" | 27.8" | 26.8" |



DAU-080M-RM-L

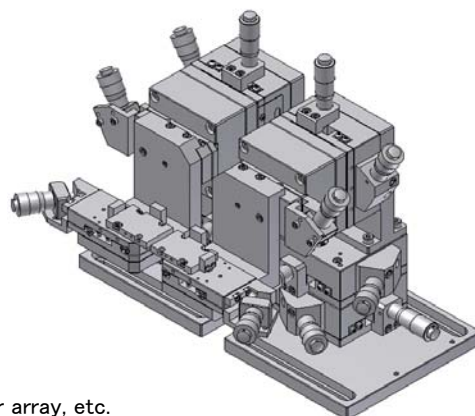
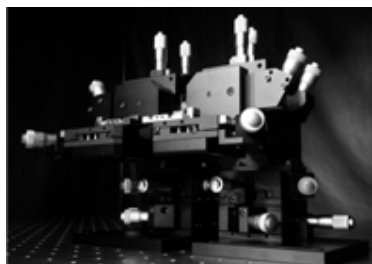
DAU-080M-RM-R

| Number of Axis | P/N |
|----------------|------------|
| 12-Axis | DAU-080M-0 |
| 6-Axis | DAU-080M-L |
| 6-Axis | DAU-080M-R |

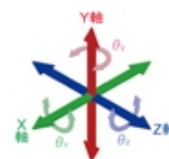
10-Axis (5-axis)

Manual Alignment Unit

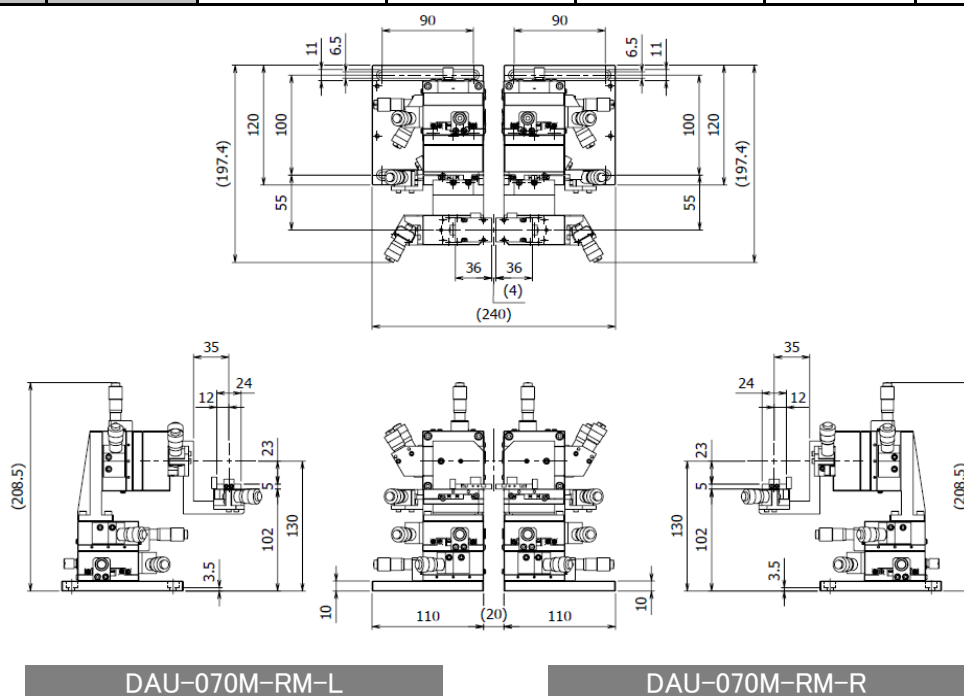
DAU-070M-0/-L/-R



- 10-axis (5-axis) manual fiber alignment unit.
- Ideal for passive device alignment such as fiber array – optical waveguide – fiber array, etc.
- With high resolution stage, alignment with excellent reproducibility is possible.
- By fixed magnet system of the holder, available to secure the position repeatability.
- By replacing the compatible holder, possible for the extension of application due to the change of device.
(Fiber holder, fiber rotation holder, the fiber array holder, etc.)

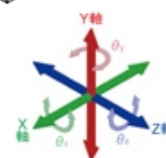
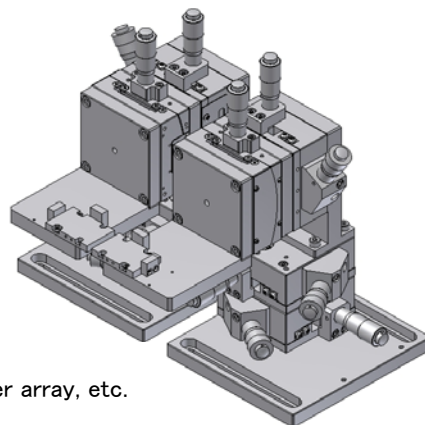
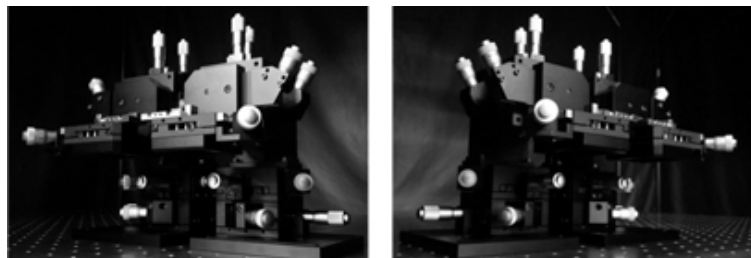


| SPEC | | | | | | |
|------------|------------|---|---|---|---------------------------|-----------------|
| P/N | Axis | X | Y | Z | θ_x | θ_y |
| | P/N | TAMF-601/R | | | GOHT-36A10 S/SR/SZ/SRZ | |
| DAU-070M-L | Travel | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | $\pm 2.5^\circ$ | $\pm 2.5^\circ$ |
| | Resolution | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | 27.8" | 27.8" |
| DAU-070M-R | Travel | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | $\pm 2.5^\circ$ | $\pm 2.5^\circ$ |
| | Resolution | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | 27.8" | 27.8" |



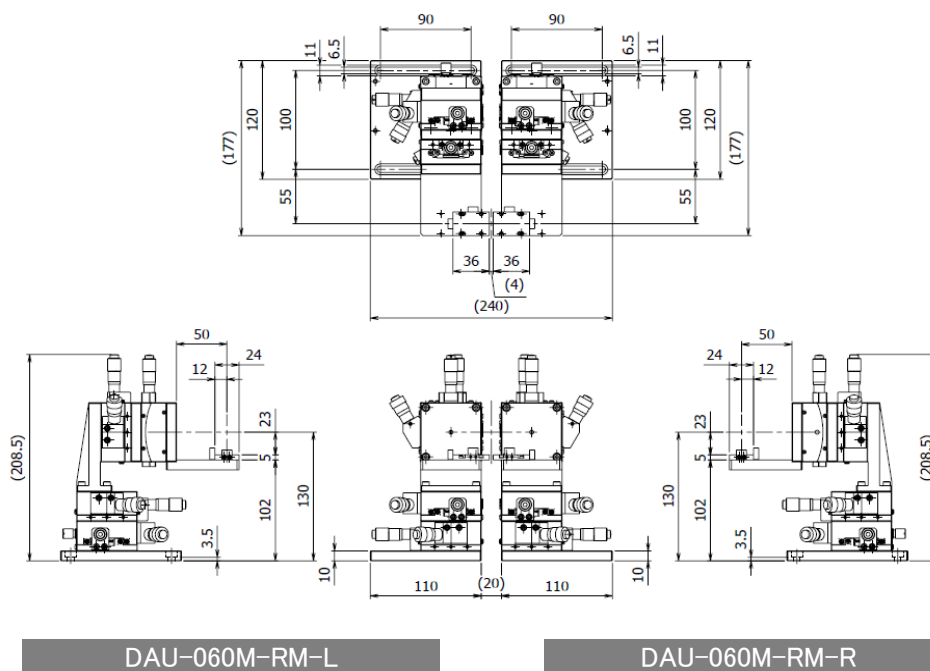
| Number of Axis | P/N |
|----------------|------------|
| 10-Axis | DAU-070M-0 |
| 5-Axis | DAU-070M-L |
| 5-Axis | DAU-070M-R |

8-Axes (4 axes) Manual Alignment Unit DAU-060M-0/-L/-R



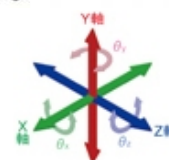
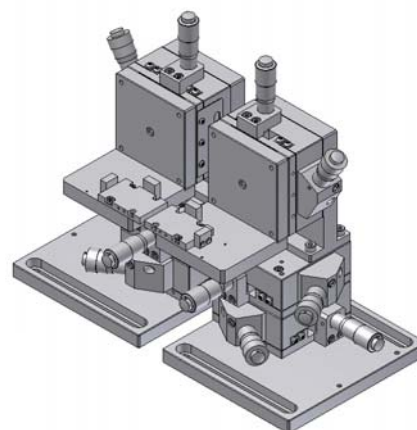
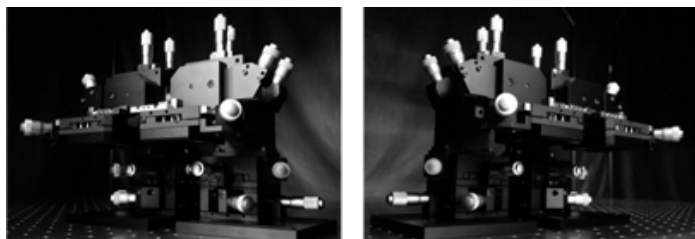
- 8-axis (4-axis) manual fiber alignment unit.
- Ideal for passive device alignment such as fiber array – optical waveguide – fiber array, etc.
- With high resolution stage, alignment with excellent reproducibility is possible.
- By fixed magnet system of the holder, available to secure the position repeatability.
- By replacing the compatible holder, possible for the extension of application due to the change of device.
(Fiber holder, fiber rotation holder, the fiber array holder, etc.)

| SPEC | | | | | |
|------------|------------|---|---|---|----------------------|
| P/N | Axis | X | Y | Z | θ_z |
| | P/N | TAMF-601/R | | | GOHT-60A60 BC/BCR |
| DAU-060M-L | Travel | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | $\pm 5^\circ$ |
| | Resolution | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | 26.8" |
| DAU-060M-R | Travel | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | $\pm 5^\circ$ |
| | Resolution | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | 26.8" |



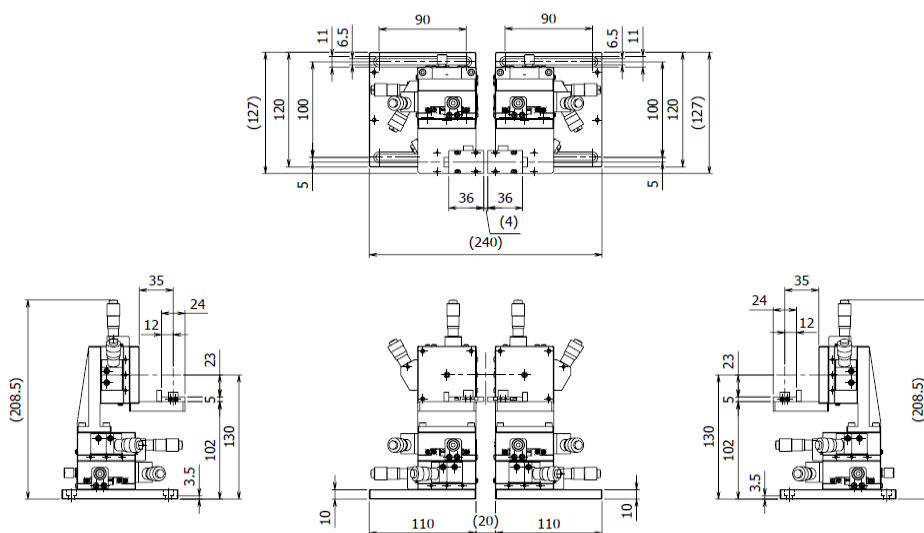
| Number of Axis | P/N |
|----------------|------------|
| 8-Axis | DAU-060M-0 |
| 4-Axis | DAU-060M-L |
| 4-Axis | DAU-060M-R |

6-Axis (3-axis) Manual Alignment Unit DAU-050M-0/-L/-R



- 8-axis (4-axis) manual fiber alignment unit.
- Ideal for passive device alignment such as fiber array – optical waveguide – fiber array, etc.
- With high resolution stage, alignment with excellent reproducibility is possible.
- By fixed magnet system of the holder, available to secure the position repeatability.
- By replacing the compatible holder, possible for the extension of application due to the change of device.
(Fiber holder, fiber rotation holder, the fiber array holder, etc.)

| SPEC | | | | |
|------------|------------|---|---|---|
| P/N | Axis | X | Y | Z |
| | P/N | TAMF-601/R | | |
| DAU-050M-L | Travel | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ |
| | Resolution | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm |
| DAU-050M-R | Travel | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ | Coarse: $\pm 6.5\text{mm}$ Fine: $\pm 0.25\text{mm}$ |
| | Resolution | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm | Coarse: 0.01mm Fine: 0.0005mm |



DAU-050M-RM-L

DAU-050M-RM-R

| Number of Axis | P/N |
|----------------|------------|
| 6-Axis | DAU-050M-0 |
| 3-Axis | DAU-050M-L |
| 3-Axis | DAU-050M-R |

Multi-Controller



■ Multi-controller that has been developed for control of the alignment equipment.

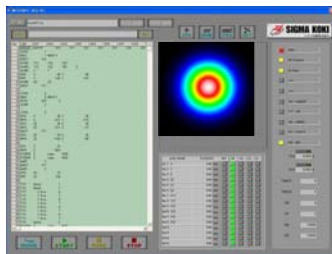
■ Original alignment software by our own development and expansion board required for equipment manufacturing are installed.

■ [ASS-02] for desktop FAPC and [ASS-04] for rack mounting FAPC are installed.

| Main Specifications | |
|---------------------|---|
| OS | Windows 7 |
| Motion 4axis / 1 | MC8042P (Nova Electronic Co., Ltd.) 4-axis independent control |
| Motion 4axis / 1 | MC8082P (Nova Electronic Co., Ltd.) 8-axis independent control |
| AD | PCI-3155 (interface Co., Ltd.) 16-bit high-speed AD converter Single-ended 16CH, 8CH differential input |
| GP-IB | PCI-4304 (interface Co., Ltd.) IEE of the FIFO equipped 488 compliant GP-IB 1CH type |

* Option (It is possible to add this board when it exceeds the number of IO driver mounted on a standard box)
 PCI-2726CM (interface Co., Ltd.)
 32-point sink-type current drive photocoupler input, 32 points high current open collector sinking output

■ Alignment Software ASS-02



- Standard type of alignment software that was coded the required function for the motion control software of multi-axis control and for the alignment.
- Commands required to the alignment are almost available, and excellent in the cost performance.
- Ideal for the device assembly equipment that the function of image observation is not necessary.

■ Alignment Software ASS-04



- A software that was added the function of the image capturing to the alignment software ASS-02.
- Perfect software to the experiment or device assembly by checking the image that can not be monitored directly such as YAG welding, etc.
- As for management of production devices, there is a data save function, and it can be output in CSV file.

| Number of Axis | P/N | Software |
|----------------|----------|----------|
| 4-Axis | SMC-04A2 | ASS-02 |
| 8-Axis | SMC-08A2 | ASS-02 |
| 8-Axis | SMC-08A4 | ASS-04 |
| 12-Axis | SMC-12A4 | ASS-04 |
| 16-Axis | SMC-16A4 | ASS-04 |

IO with Micro-step Driver Box

■ SDB-04 for 4-axis for DC.IN type Micro-step Driver BOX



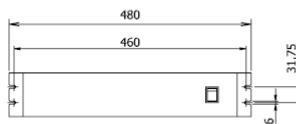
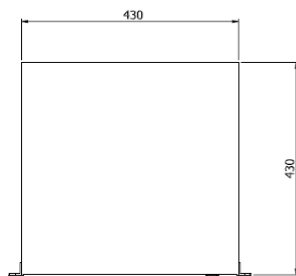
- Best for the facility development and manufacturing of the alignment equipment.
- Flat-screen specification for 19-inch rack-mount type (1U).
- Design of the same shape with an emphasis on scalability.
- Compact design with a built-in drive power.
- Can control high-precision suitable for the application because of the possibility of 16 types (micro steps).
- As a standard device, equipped with the digital IO needed to the equipment for the remote control of peripheral equipment and the drive signal tower of the solenoid valve.

■ SDB-08 for 8-axis DC.IN Type Micro-step Driver BOX

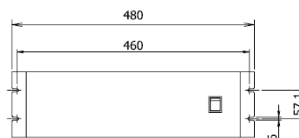
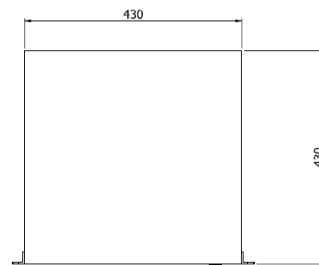


- Best for the facility development and manufacturing of the alignment equipment.
- Flat-screen specification for 19-inch rack-mount type (2U).
- Design of the same shape with an emphasis on scalability.
- Compact design with a built-in drive power.
- Can control high-precision suitable for the application because of the possibility of 16 types (micro steps).
- As a standard device, equipped with the digital IO needed to the equipment for the remote control of peripheral equipment and the drive signal tower of the solenoid valve.

Outline Drawing



SDB-04



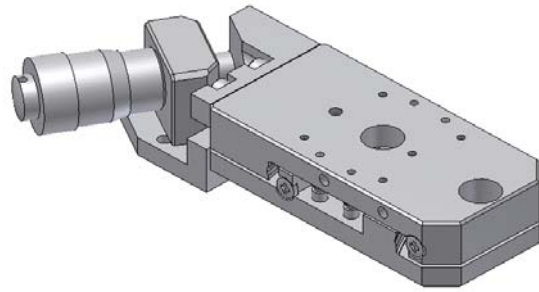
SDB-08

GOHT-36A10/S/SR/SZ/SRZ

α -axis tilt goniometer stage

Feature

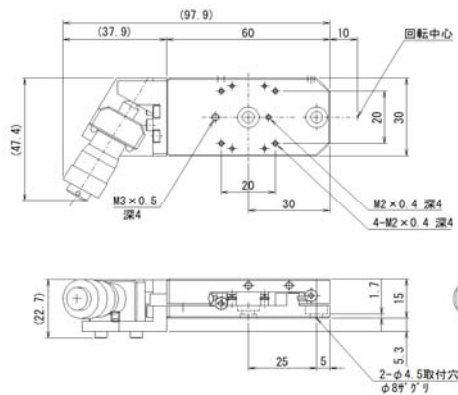
- High rigidity by integral guide
- High durability
- Small and small space



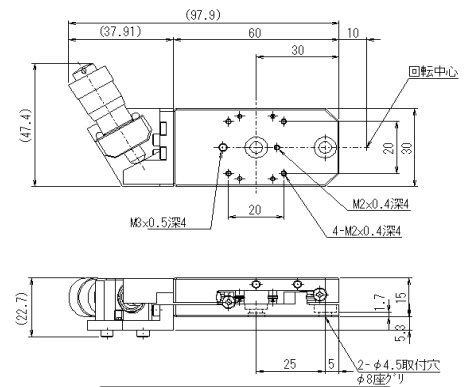
SPEC

| | Parallelism (μ m) | Rotation Center Height (mm) | Travel | Travel per Knob Rotation | Max. Moment Capacity (N·m) | | Moment Stiffness ($^{\circ}$ /N·cm) | | Load Capacity [N] | Weight (kg) |
|----------------|---------------------------|-----------------------------------|-------------------|-----------------------------|----------------------------------|------|--|-----|-------------------------|----------------|
| Specifications | 30 | 10 | $\pm 2.5^{\circ}$ | $\cong 27.6$ | Fx | Fy | Fx | Fy | 29.4 | 0.25 |
| | | | | | 0.015 | 0.01 | 0.5 | 1.5 | | |

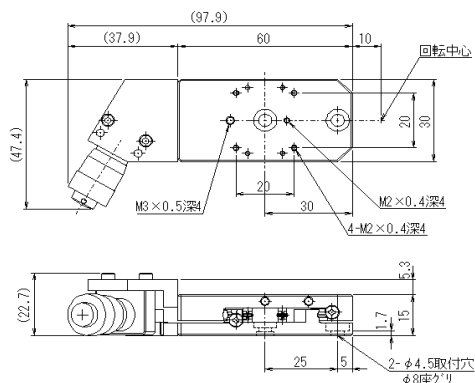
Outline Drawing



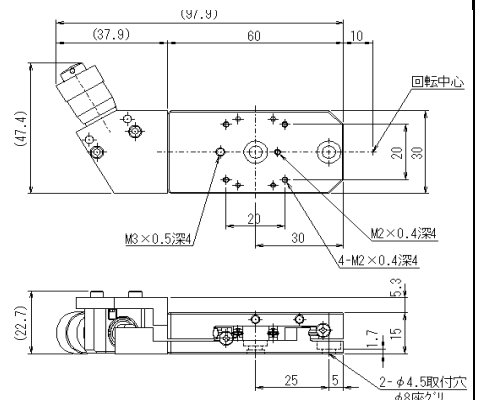
GOHT-36A10S



GOHT-36A10SR



GOHT-36A10SZ



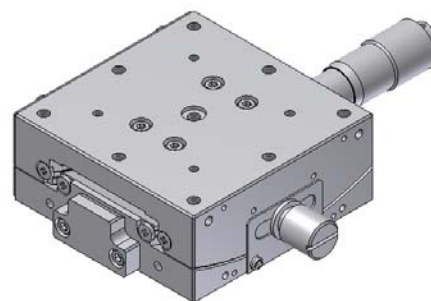
GOHT-36A10SRZ

GOHT-60A60/BC/BCR

α -axis micro-type guide integrated goniometer stage

Feature

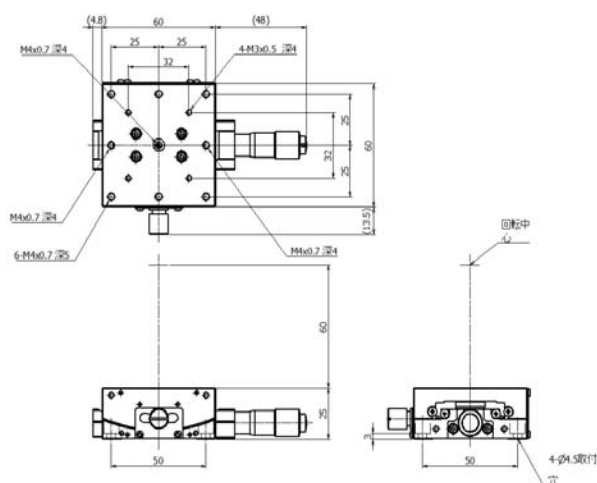
- High rigidity by integral guide
- High durability
- High-precision rotation center



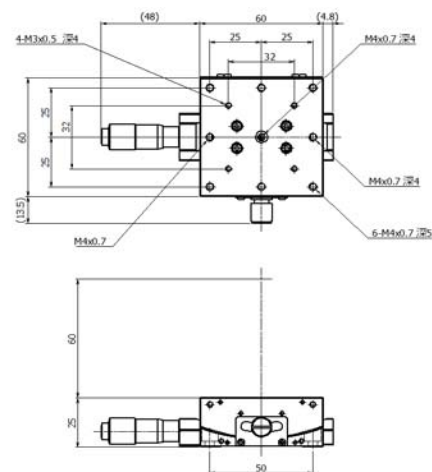
SPEC

| | Parallelism (μ m) | Rotation Center Height (mm) | Travel | Resolution "/1DIV | Rotation Center Displacement (mm) | Max. Moment Capacity (N·m) | | | Moment Stiffness (" /N·cm) | | Load Capacity (N) | Weight (kg) |
|----------------|---------------------------|-----------------------------------|---------------|----------------------|---|----------------------------------|----|------------|----------------------------------|-----|-------------------------|----------------|
| Specifications | 30 | 60 | $\pm 5^\circ$ | $\div 26.8$ | $\phi 0.01$ | Fx | Fy | F θ | Fx | Fy | 98 | 0.4 |
| | | | | | | 3 | 6 | 3 | 0.3 | 0.3 | | |

Outline Drawing



GOHT-60A60BC



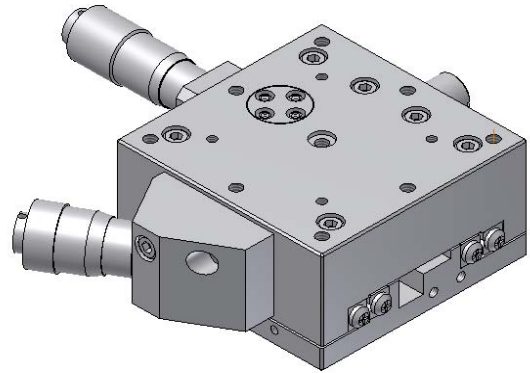
GOHT-60A60BCR

TAMF-601/R

X-axis coarse and fine type aluminum cross roller stage

Feature

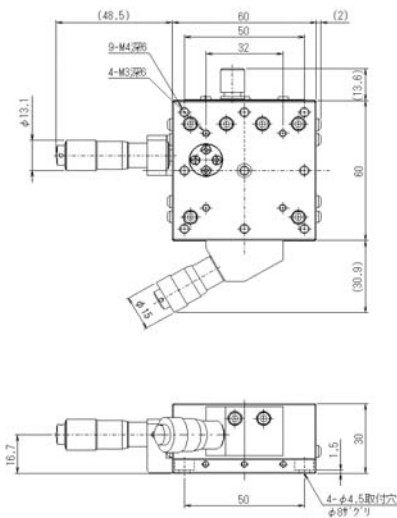
- Coarse and fine control
- High resolution
- High rigidity



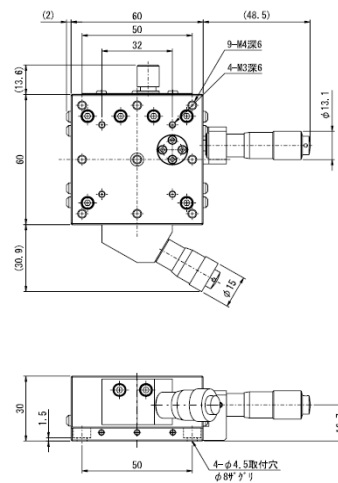
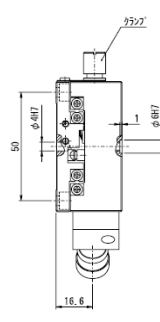
SPEC

| | Parallelism (μm) | Running Parallelism (μm) | Perpendicularity (μm) | Pitch ($''$) | Yaw ($''$) | Max. Moment Capacity (N·cm) | | | Moment Stiffness ($''$ /N·cm) | | | Load Capacity (N) | Resolution Fine (mm) | Travel (mm) | | Readable Resolution (μm) | |
|----------------|----------------------------------|---|---------------------------------------|-------------------|-----------------|-----------------------------------|-----|------------|--------------------------------------|-----|------------|-------------------------|-------------------------|----------------|------------|---|------|
| Specifications | 30 | 10 | 2 | 20 | 10 | Fx | Fy | F θ | Fx | Fy | F θ | 4.9 | 0.0005 or less | Coarse | Fine | Coarse | Fine |
| | | | | | | 8.6 | 6.4 | 5.6 | 0.1 | 0.1 | 0.1 | | | ± 6.5 | ± 0.25 | 10 | 0.5 |

Outline Drawing



TAMF-601



TAMF-601R

TAMM

Aluminum cross roller motorized stage



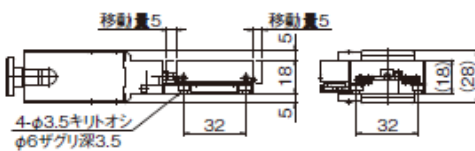
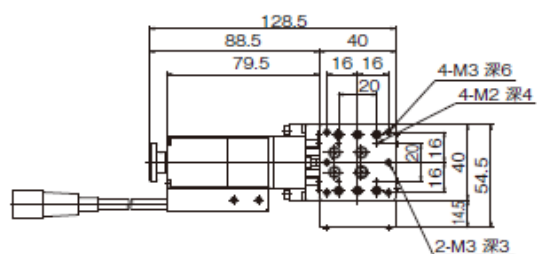
Feature

- Lightweight
- Compact slim body
- High durability
- High Repeatability
- Cost performance

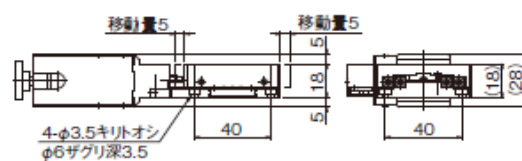
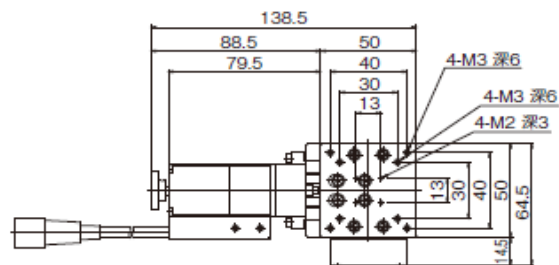
SPEC

| Part Number | | TAMM40-10C | TAMM50-10C | TAMM60-15C | TAMM70-15C |
|---------------------------|--------------------------|---|-------------|---|-------------|
| Opposite Model | | TAMM40-10CR | TAMM50-10CR | TAMM60-15CR | TAMM70-15CR |
| Mechanical Specifications | Travel | 10mm | 10mm | 15mm | 15mm |
| | Table Size | 40 × 40mm | 50 × 50mm | 60 × 60mm | 70 × 70mm |
| | Feed Screw | Ball screw diameter ϕ 4mm,1mm lead | | Ball screw diameter ϕ 6mm,1mm lead | |
| | Positioning Slide | Crossed roller | | | |
| | Stage Material | Aluminum – Black anodized | | | |
| | Weight | 0.33kg | 0.37kg | 0.48kg | 0.53kg |
| Accuracy Specifications | Resolution | 2 μ m/pulse (Full) 1 μ m/pulse (Half) | | | |
| | MAX Speed | 10mm/sec | | | |
| | Positioning Accuracy | <6 μ m | | | |
| | Positional Repeatability | <1 μ m | | | |
| | Load Capacity | 29.4N【3.0kgf】 | 49N【5.0kgf】 | | |
| | Moment Stiffness | 1.5'' /N•cm | | 0.5'' /N•cm | |
| | Lost Motion | <1 μ m | | | |
| | Backlash | <1 μ m | | | |
| | Parallelism | <30 μ m | | | |
| | Running Parallelism | <10 μ m | | | |
| | Pitch/Yaw | <15'' | | | |
| Sensor | Sensor Part Number | Micro photo sensor: GP1S097HCZ (Sharp Corporation): Limit sensor, origin sensor | | | |
| | Limit Sensor | Equipped (NORMAL CLOSE) | | | |
| | Origin Sensor | Equipped (NORMAL OPEN) | | | |
| | Proximity Origin Sensor | None | | | |
| Motor | Type | 5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.) | | | |
| | Motor Part Number | C9863-90215P (□28mm) | | | |
| | Step Angle | 0.72° | | | |
| Sensor | Power Voltage | DC+5V~+24V | | | |
| | Current Consumption | 60mA or lower (20mA or lower per sensor) | | | |
| | Control Output | NPN open collector output 50mA | | | |
| | Output Logic | When shaded: Output transistor OFF (no conduction): Limit sensor When shaded: Output transistor ON (conduction): Origin sensor | | | |

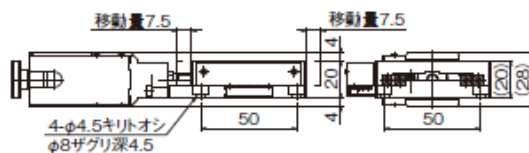
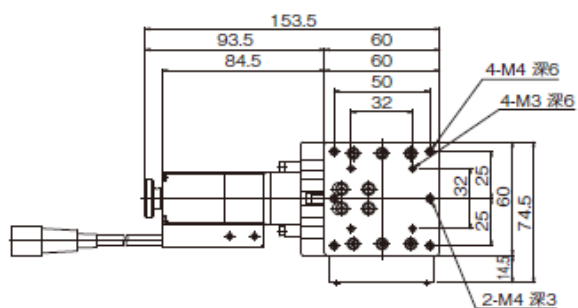
TAMM40-10C



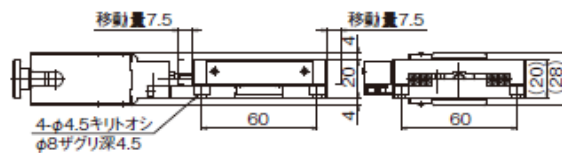
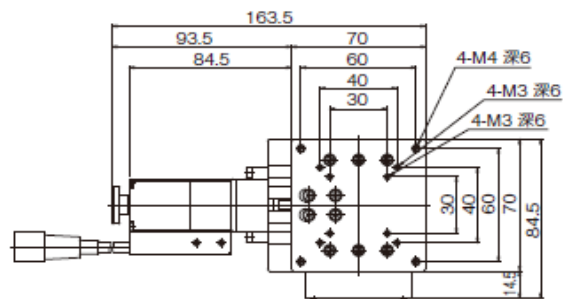
TAMM50-10C



TAMM60-15C



TAMM70-15C

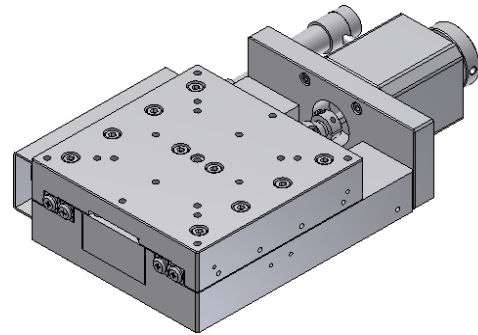


TAMM/TSMM

Aluminum / steel cross roller stage

Feature

- High rigidity
- High durability
- High Repeatability
- Cost performance

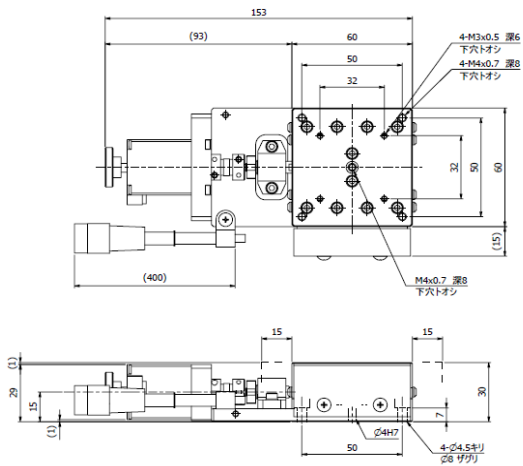


SPEC

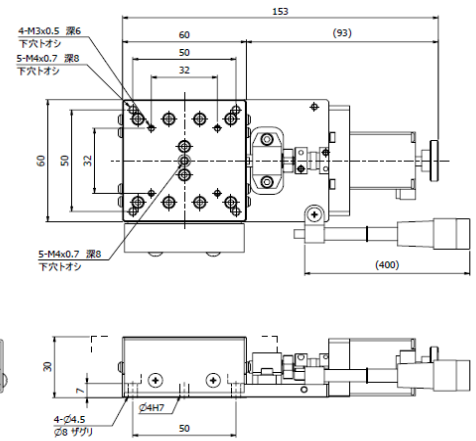
| Part Number | | TSMM60-30X | TAMM100-50X | TSMM100-50X |
|---------------------------|--------------------------|---|---------------------------------------|---------------------------------------|
| Opposite Model | | TSMM60-30XR | TAMM100-50XR | TSMM100-50XR |
| Mechanical Specifications | Travel | 30mm | 50mm | 50mm |
| | Table Size | 60 × 60mm | 100 × 100mm | 100 × 100mm |
| | Feed Screw | Ball screw diameter ϕ 4mm,1mm lead | Ball screw diameter ϕ 6mm,1mm lead | |
| | Positioning Slide | Crossed roller | | |
| | Stage Material | Steel – Super black chrome | Aluminum – Black anodized | Steel – Super black chrome |
| | Weight | 1kg | 1.9kg | 3kg |
| Accuracy Specifications | Resolution | 2 μ m/pulse (Full) 1 μ m/pulse (Half) | 2 μ m/pulse (Full) 1 μ m/pulse (Half) | 2 μ m/pulse (Full) 1 μ m/pulse (Half) |
| | MAX Speed | 10mm/sec | 10mm/sec | |
| | Positioning Accuracy | <6 μ m | <6 μ m | |
| | Positional Repeatability | <1 μ m | <1 μ m | |
| | Load Capacity | 68.6N【7.0kgf】 | 98N【10.0kgf】 | |
| | Moment Stiffness | 0.05″ /N・cm | 0.05″ /N・cm | 0.03″ /N・cm |
| | Lost Motion | <1 μ m | <1 μ m | |
| | Backlash | <1 μ m | <1 μ m | |
| | Parallelism | <30 μ m | <30 μ m | |
| | Running Parallelism | <10 μ m | <10 μ m | |
| | Pitch/Yaw | <15″ | <15″ | |
| Sensor | Sensor Part Number | Micro photo sensor: GP1S097HCZ (Sharp Corporation): Limit sensor, origin sensor | | |
| | Limit Sensor | Equipped (NORMAL CLOSE) | | |
| | Origin Sensor | Equipped (NORMAL OPEN) | | |
| | Proximity Origin Sensor | None | | |

| | | | |
|--------|---------------------|--|-----------------------|
| Motor | Type | 5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.) | |
| | Motor Part Number | SH5281-7215 (□28mm) | TS3667N43E967 (□42mm) |
| | Step Angle | 0,72° | |
| Sensor | Power Voltage | DC+5V~+24V | |
| | Current Consumption | 60mA or lower (20mA or lower per sensor) | |
| | Control Output | NPN open collector output 50mA | |
| | Output Logic | When shaded: Output transistor OFF (no conduction): Limit sensor | |
| | | When shaded: Output transistor ON (conduction): Origin sensor | |

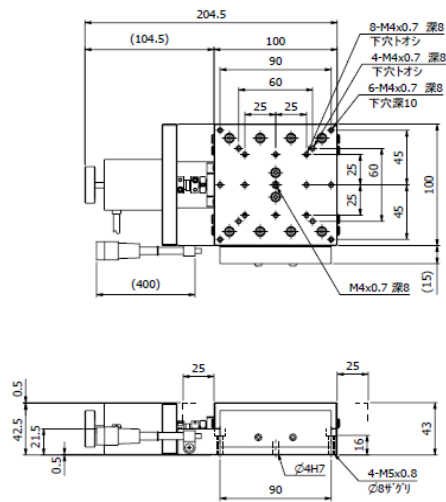
Outline Drawing



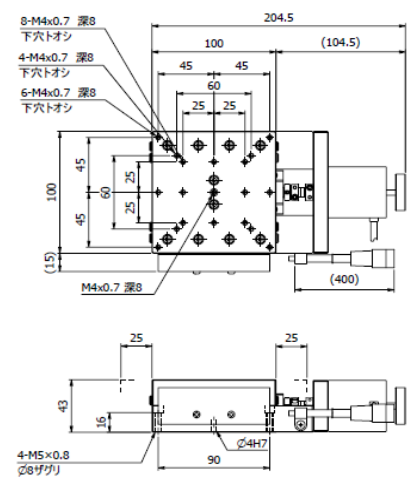
TSM60-30X



TSM60-30XR



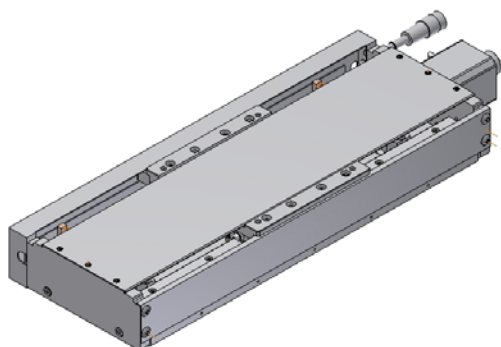
TMM/TSMM100-50X



TMM/TSMM100-50XR

KLSA/KLSS

Linear guide stage



Feature

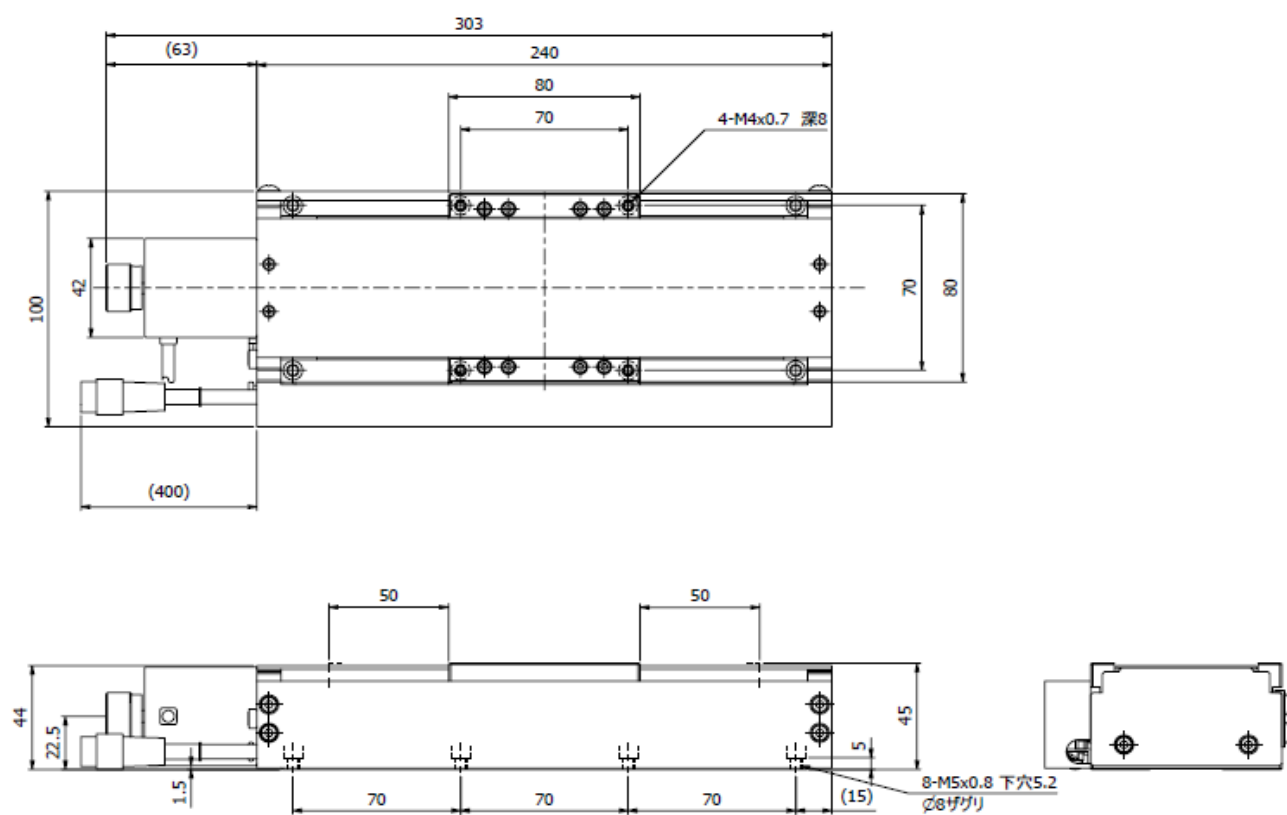
- Long stroke
- High durability
- High Repeatability
- High cost performance

SPEC

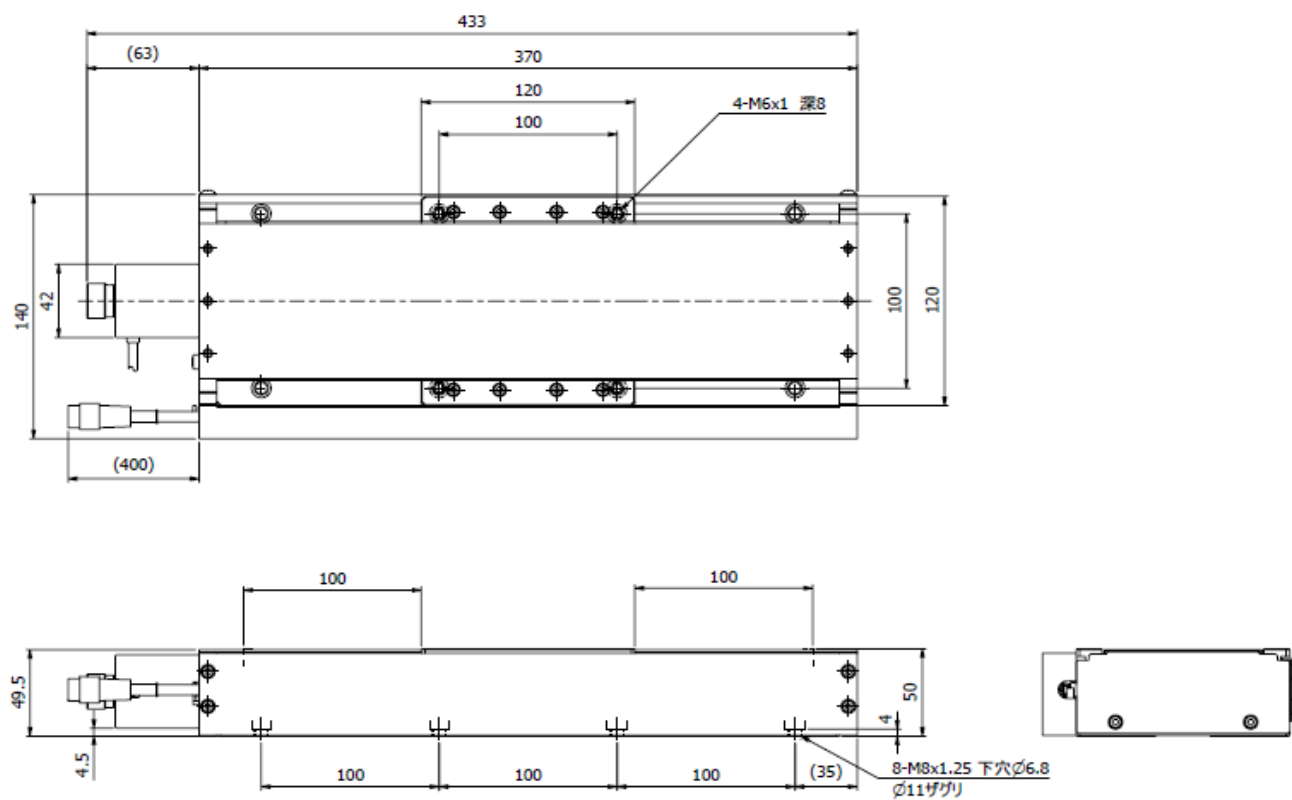
| Part Number | | KLSA-100X | KLSS-100X | KLSA-200X | KLSS-200X |
|---------------------------|--------------------------|--|------------|--|------------|
| Opposite Model | | KLSA-100XR | KLSS-100XR | KLSA-200XR | KLSS-200XR |
| Mechanical Specifications | Travel | 100mm | | 200mm | |
| | Table Size | 80 × 80mm | | 120 × 120mm | |
| | Feed Screw | Ball screw diameter ϕ 8mm , 1mm lead | | Ball screw diameter ϕ 10mm , 5mm lead | |
| | Positioning Slide | Linear bearing | | | |
| | Stage Material | Aluminum | Steel | Aluminum | Steel |
| | Weight | 2.2kg | 3.5kg | 5.1kg | 7.7kg |
| Accuracy Specifications | Resolution | 4 μ m/pulse (Full) 2 μ m/pulse (Half) | | 10 μ m/pulse (Full) 5 μ m/pulse (Half) | |
| | MAX Speed | 30mm/sec | | 50mm/sec | |
| | Positioning Accuracy | < 15 μ m | | < 20 μ m | |
| | Positional Repeatability | < \pm 1 μ m | | | |
| | Load Capacity | 147N【15kgf】 | | 294N【30kgf】 | |
| | Moment Stiffness | 0.05″ /N・cm | | 0.02″ /N・cm | |
| | Lost Motion | < 4 μ m | | | |
| | Backlash | < 1 μ m | | | |
| | Parallelism | < 50 μ m | | | |
| | Running Parallelism | < 10 μ m | | | |
| | Pitch/Yaw | < 20″ /15″ | | | < 40″ /20″ |
| Sensor | Sensor Part Number | Micro photo sensor: PM-L24 (SUNX Co., Ltd.): Limit sensor, origin sensor | | | |
| | Limit Sensor | Equipped (NORMAL CLOSE) | | | |
| | Origin Sensor | Equipped (NORMAL OPEN) | | | |
| | Proximity Origin Sensor | None | | | |

| | | |
|--------|---------------------|---|
| Motor | Type | 5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.) |
| | Motor Part Number | PK545-NBW (□42mm) |
| | Step Angle | 0.72° |
| Sensor | Power Voltage | DC+5V~+24V |
| | Current Consumption | 45mA or lower (15mA per sensor) |
| | Control Output | NPN open collector output 50mA |
| | Output Logic | When shaded: Output transistor OFF (no conduction): Limit sensor When shaded: Output transistor ON (conduction): Origin sensor |

Outline Drawing



KLSS-100X



KLSS-200X

GOHTM □40mm/□50mm

Guide integrated goniometer stage



GOHTM-40A**



GOHTM-50A**

Feature

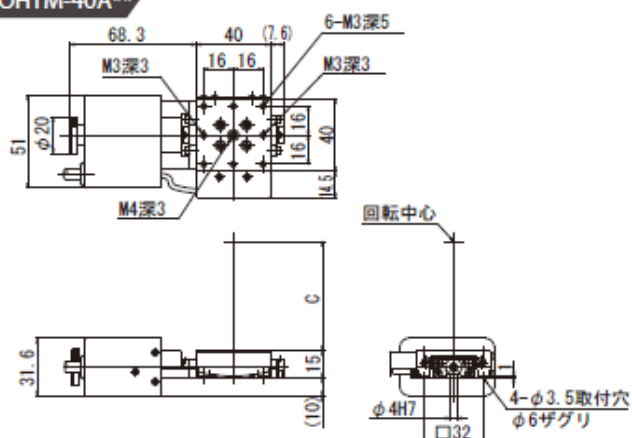
- High precision •high rigidity •high durability
- High cost performance
- Rotation center accuracy improvement
- A wealth of variation in height center of rotation
- Enhancement of the stage size (□ 40/50/60/70mm)

SPEC

| Part Number | | GOHTM-40A60 | GOHTM-40A75 | GOHTM-50A50 | GOHTM-50A68 | GOHTM-50A86 |
|---------------------------|-------------------------------------|---|-------------------|---|-------------------|-------------------|
| Opposite model | | GOHTM-40A60R | GOHTM-40A75R | GOHTM-50A50R | GOHTM-50A68R | GOHTM-50A86R |
| Mechanical Specifications | Travel | ±5° | ±4° | ±10° | ±8° | ±6° |
| | Table Size | 40 × 40mm | | 50 × 50mm | | |
| | Positioning Slide | Extended Contact Ball Guide | | Extended Contact Ball Guide | | |
| | Travel Mechanism | Worm gear (1:232) | Worm gear (1:406) | Worm gear (1:232) | Worm gear (1:300) | Worm gear (1:375) |
| | Stage Material | SUS440C quench hardened – Electroless nickel | | | | |
| | Weight | 0.4kg | 0.4kg | 0.9kg | 0.9kg | 0.9kg |
| Size Tolerance | Stage Height | 15mm | | 18mm | | |
| | Rotation Center Height | 60±0.1 | 75±0.1 | 50±0.1 | 68±0.1 | 86±0.1 |
| | Rotation Center Deflection Accuracy | < φ 0.01mm | | < φ 0.01mm | | |
| Accuracy Specifications | Resolution (Full) | ≒0.00217° /pulse | ≒0.00177° /pulse | ≒0.00310° /pulse | ≒0.0024° /pulse | ≒0.00192° /pulse |
| | (Half) | ≒0.00108° /pulse | ≒0.00089° /pulse | ≒0.00155° /pulse | ≒0.0012° /pulse | ≒0.00096° /pulse |
| | MAX Speed | 10° /sec | 8.9° /sec | 9.3° /sec | 7.2° /sec | 5.8° /sec |
| | Positional Repeatability | < ±0.004° | | | | |
| | Load Capacity | 19.6N【2.0kgf】 | | 29.4N【3.0kgf】 | | |
| | Moment Stiffness | Roll 0.6″/N・cm Yaw 0.6″/N・cm | | Roll 0.4″/N・cm Yaw 0.4″/N・cm | | |
| | Lost Motion | 0.02° | | | | |
| Sensor | Sensor Part Number | Micro photo sensor: GP1S097HCZ (Sharp Corporation): Limit sensor, origin sensor | | Micro photo sensor: GP1S097HCZ (Sharp Corporation): Limit sensor, origin sensor | | |
| | Limit Sensor | Equipped (NORMAL CLOSE) | | Equipped (NORMAL CLOSE) | | |
| | Origin Sensor | None | | Equipped (NORMAL OPEN) | | |
| | Proximity Origin Sensor | None | | None | | |
| | | | | | | |
| Motor | Type | 5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.) | | 5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.) | | |
| | Motor Part Number | C9863-90215P (□28mm) | | TS3667N43E7 (□42mm) | | |
| | Step Angle | 0.72° | | 0.72° | | |
| Sensor | Power Voltage | DC+5V～+24V | | DC+5V～+24V | | |
| | Current Consumption | 40mmA or lower (20mA per sensor) | | 60mmA or lower (20mA per sensor) | | |
| | Control Output | NPN open collector output 50mA | | NPN open collector output 50mA | | |
| | Output Logic | | | When shaded: Output transistor OFF (no conduction): Limit sensor | | |
| | | When shaded: Output transistor ON (conduction)) | | When shaded: Output transistor ON (conduction): Origin sensor | | |

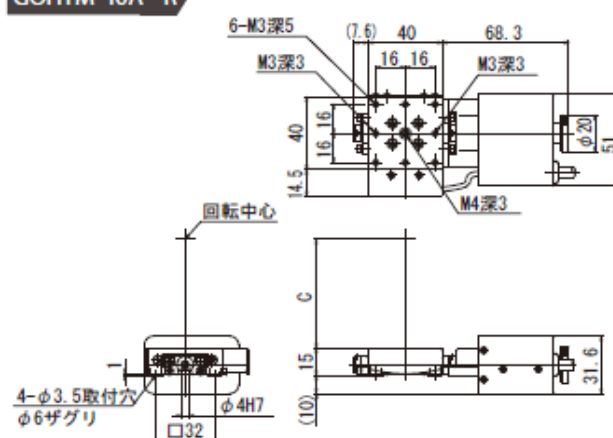
Outline Drawing

GOHTM-40A**



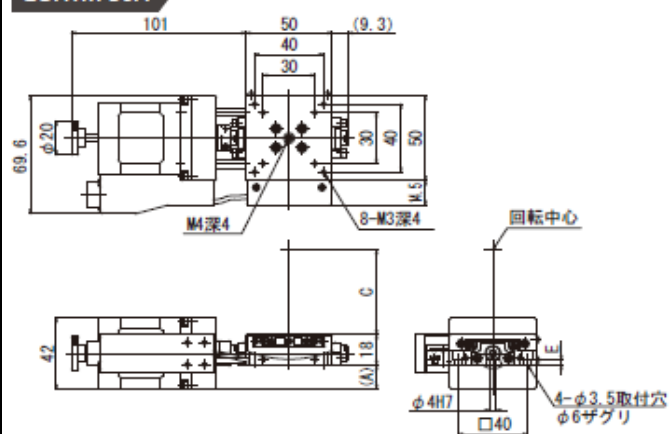
| 品番 | C (mm) |
|-------------|--------|
| GOHTM-40A60 | 60 |
| GOHTM-40A75 | 75 |

GOHTM-40A**R



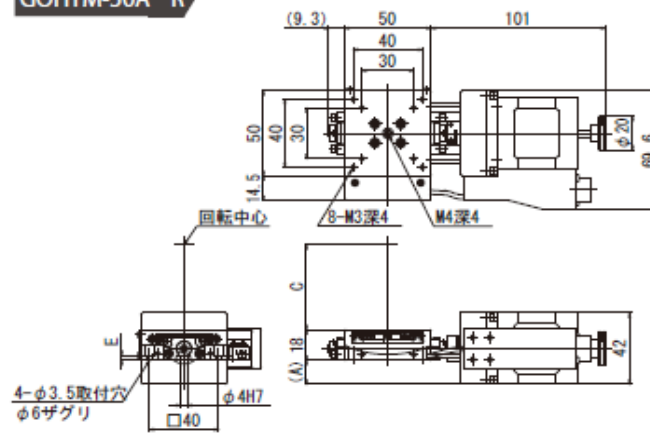
| 品番 | C (mm) |
|--------------|--------|
| GOHTM-40A60R | 60 |
| GOHTM-40A75R | 75 |

GOHTM-50A**



| 品番 | A (mm) | C (mm) | E (mm) |
|-------------|--------|--------|--------|
| GOHTM-50A50 | 14 | 50 | 3 |
| GOHTM-50A68 | 13 | 68 | 3 |
| GOHTM-50A86 | 14 | 86 | 2 |

GOHTM-50A**R



| 品番 | A (mm) | C (mm) | E (mm) |
|--------------|--------|--------|--------|
| GOHTM-50A50R | 14 | 50 | 3 |
| GOHTM-50A68R | 13 | 68 | 3 |
| GOHTM-50A86R | 14 | 86 | 2 |

Guide integrated goniometer stage



GOHTM-40A**



GOHTM-50A**

Feature

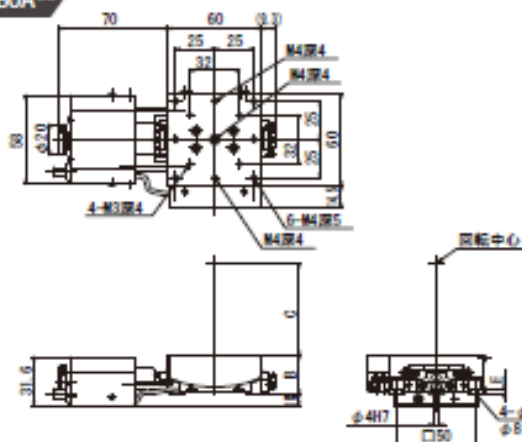
- High precision • high rigidity • high durability
- High cost performance
- Rotation center accuracy improvement
- A wealth of variation in height center of rotation
- Enhancement of the stage size (□ 40/50/60/70mm)

SPEC

| Part Number | | GOHTM-60A60 | GOHTM-60A85 | GOHTM-60A105 | GOHTM-70A70 | GOHTM-70A96 | GOHTM-70A122 |
|---------------------------|-------------------------------------|---|-------------------|-------------------|---|-------------------|-------------------|
| Opposite Model | | GOHTM-60A60R | GOHTM-60A85R | GOHTM-60A105R | GOHTM-70A70R | GOHTM-70A96R | GOHTM-70A122R |
| Mechanical Specifications | Travel | ±14° | ±9° | ±7° | ±10° | ±8° | ±6° |
| | Table Size | 60×60mm | | | 70×70mm | | |
| | Positioning Slide | Extended Contact Ball Guide | | | Extended Contact Ball Guide | | |
| | Travel Mechanism | Worm gear (1:246) | Worm gear (1:314) | Worm gear (1:380) | Worm gear (1:274) | Worm gear (1:360) | Worm gear (1:450) |
| | Stage Material | SUS440C quench hardened – Electroless nickel | | | SUS440C quench hardened – Electroless nickel | | |
| | Weight | 0.85kg | 0.75kg | 0.75kg | 1.45kg | 1.45kg | 1.45kg |
| Size Tolerance | Stage Height | 25mm | 20mm | 20mm | 26mm | 26mm | 26mm |
| | Rotation Center Height | 60±0.1 | 85±0.1 | 105±0.1 | 70±0.1 | 96±0.1 | 122±0.1 |
| | Rotation Center Deflection Accuracy | < φ 0.01mm | | | < φ 0.01mm | | |
| Accuracy Specifications | Resolution (Full) | ≒0.00293° /pulse | ≒0.00229° /pulse | ≒0.00198° /pulse | ≒0.00263° /pulse | ≒0.002° /pulse | ≒0.0016° /pulse |
| | (Half) | ≒0.00146° /pulse | ≒0.00115° /pulse | ≒0.00095° /pulse | ≒0.00131° /pulse | ≒0.001° /pulse | ≒0.0008° /pulse |
| | MAX Speed | 10° /sec | 8° /sec | 6.6° /sec | 7.8° /sec | 6° /sec | 4.8° /sec |
| | Positional Repeatability | < ±0.004° | | | | | |
| | Load Capacity | 29.4N【3.0kgf】 | | | 49N【5.0kgf】 | | |
| | Moment Stiffness | Roll 0.3″/N・cm Yaw 0.3″/N・cm | | | Roll 0.1″/N・cm Yaw 0.1″/N・cm | | |
| | Lost Motion | 0.02° | | | | | |
| Sensor | Sensor Part Number | Micro photo sensor: GP1S097HCZ (Sharp Corporation) : Limit sensor, origin sensor | | | Micro photo sensor: GP1S097HCZ (Sharp Corporation) : Limit sensor, origin sensor | | |
| | Limit Sensor | Equipped (NORMAL CLOSE) | | | Equipped (NORMAL CLOSE) | | |
| | Origin Sensor | Equipped (NORMAL OPEN) | | | Equipped (NORMAL OPEN) | | |
| | Proximity Origin Sensor | None | | | None | | |

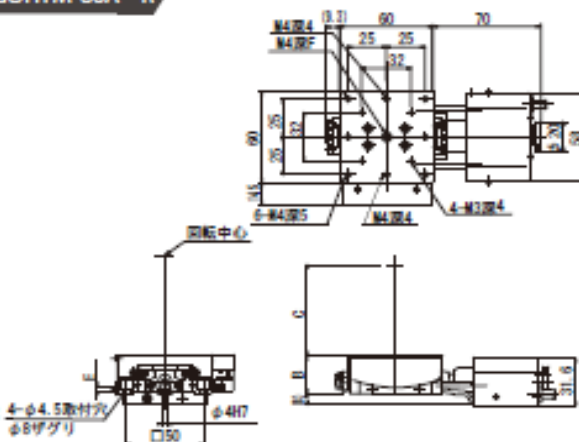
| | | | |
|--------|---------------------|---|--|
| Motor | Type | 5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.) | 5-phase stepping motor 0.75A/phase (Tamagawa Seiki Co., Ltd.) |
| | Motor Part Number | C9863-90215P (□28mm) | TS3667N43E7 (□42mm) |
| | Step Angle | 0.72° | 0.72° |
| Sensor | Power Voltage | DC+5V~+24V | DC+5V~+24V |
| | Current Consumption | 60mA or lower (20mA per sensor) | 60mA or lower (20mA per sensor) |
| | Control Output | NPN open collector output 50mA | NPN open collector output 50mA |
| | Output Logic | When shaded: Output transistor OFF (no conduction): When shaded: Output transistor ON (conduction) | When shaded: Output transistor OFF (no conduction): When shaded: Output transistor ON (conduction): Origin sensor |

GOHTM-60A**



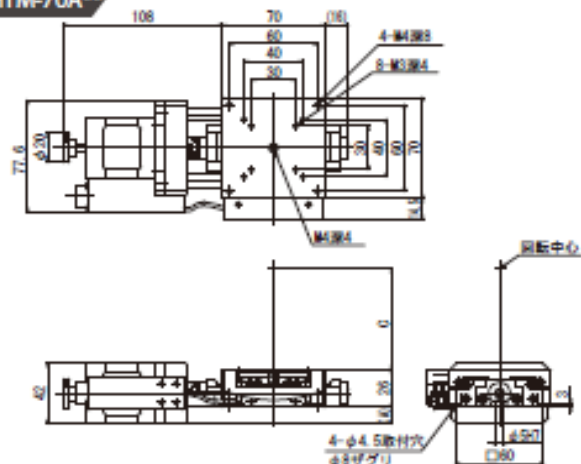
| 品番 | A (mm) | C (mm) | E (mm) |
|--------------|--------|--------|--------|
| GOHTM-60A60 | 25 | 60 | 3 |
| GOHTM-60A85 | 20 | 85 | 2 |
| GOHTM-60A105 | 20 | 105 | 2 |

GOHTM-60A**R



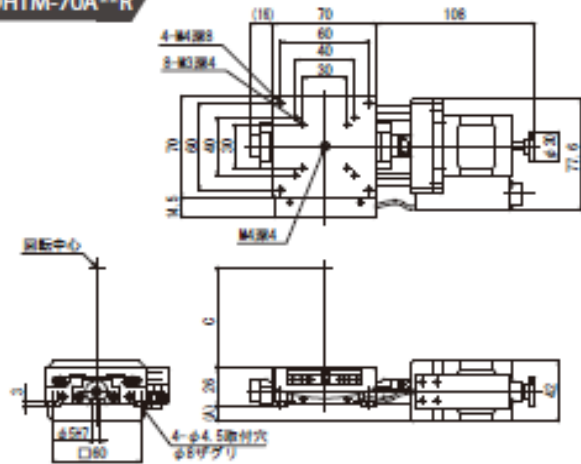
| 品番 | A (mm) | C (mm) | E (mm) |
|---------------|--------|--------|--------|
| GOHTM-60A60R | 25 | 60 | 3 |
| GOHTM-60A85R | 20 | 85 | 2 |
| GOHTM-60A105R | 20 | 105 | 2 |

GOHTM-70A**



| 品番 | A (mm) | C (mm) |
|--------------|--------|--------|
| GOHTM-70A70 | 11 | 70 |
| GOHTM-70A96 | 13 | 96 |
| GOHTM-70A122 | 14 | 122 |

GOHTM-70A**R



| 品番 | A (mm) | C (mm) |
|---------------|--------|--------|
| GOHTM-70A70R | 11 | 70 |
| GOHTM-70A96R | 13 | 96 |
| GOHTM-70A122R | 14 | 122 |

SGSP-YAW

Rotation Motorized Stages



Feature

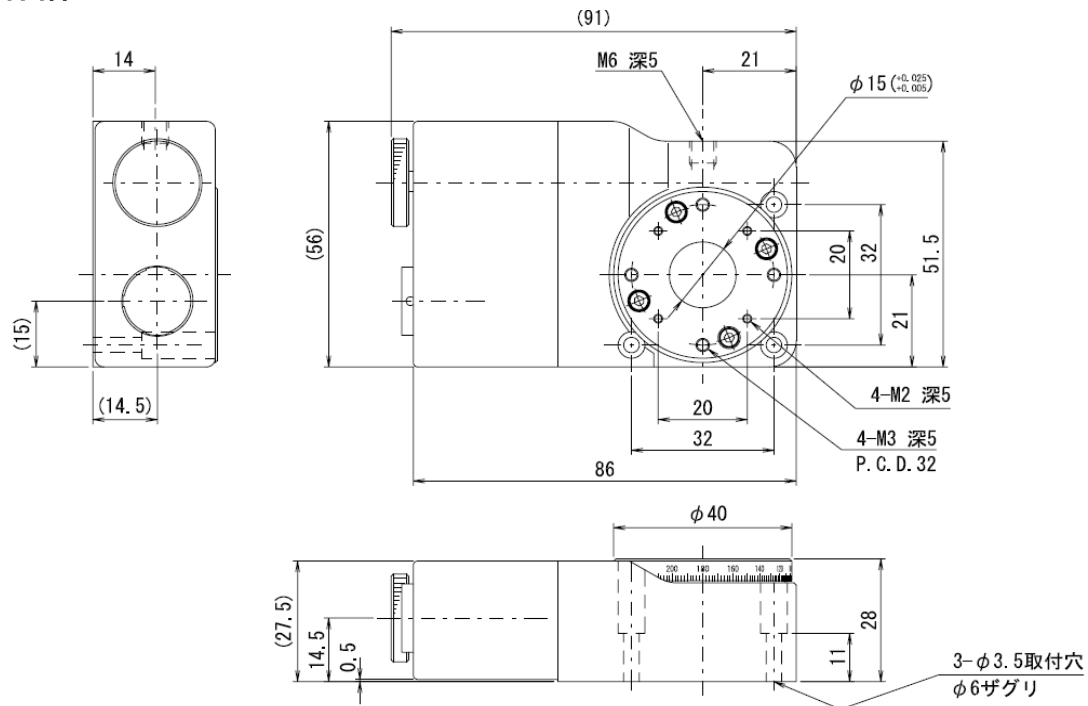
High performance motorized rotation stage that is combined of compact and high rigidity by our own space-saving design

SPEC

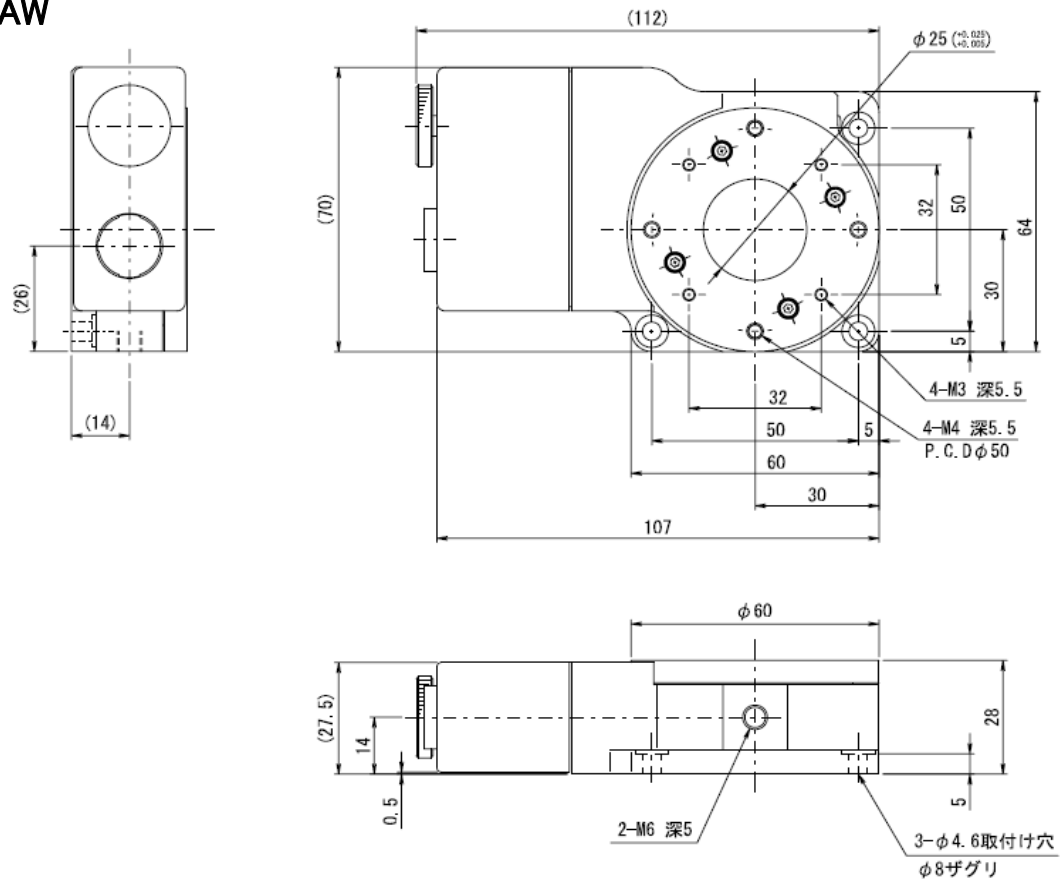
| Part Number | | SGSP-40YAW | SGSP-60YAW-0B | SGSP-80YAW | SGSP-120YAW |
|---------------------------|------------------------------------|--|------------------------------|--------------------------------|--------------------------------|
| Mechanical Specifications | Rotation Range | Move in the counterclockwise CCW direction to ∞ , and stop at near 0 degree (-2.5°) in the clockwise CW direction. | | | |
| | Table Size | $\phi 40\text{mm}$ | $\phi 60\text{mm}$ | $\phi 80\text{mm}$ | $\phi 120\text{mm}$ |
| | Travel Mechanism (reduction ratio) | Worm gear (1:144) | | | |
| | Positioning Slide | Bearing method | Crossed roller | Crossed roller | Crossed roller |
| | Stage Material | Aluminum / Aluminum bronze | | | |
| | Weight | 0.35kg | 0.45kg | 1.1kg | 2.0kg |
| Accuracy Specifications | Resolution (Full) | 0.005° /pulse | 0.005° /pulse | 0.005° /pulse | 0.005° /pulse |
| | (Half) | 0.0025° /pulse | 0.0025° /pulse | 0.0025° /pulse | 0.0025° /pulse |
| | MAX Speed | 30° /sec | 30° /sec | 30° /sec | 30° /sec |
| | Positioning Accuracy | $<0.1^\circ$ | $<0.1^\circ$ | $<0.15^\circ$ | $<0.1^\circ$ |
| | Positional Repeatability | $<0.020^\circ$ | $<0.020^\circ$ | $<0.020^\circ$ | $<0.020^\circ$ |
| | Load Capacity | 19.6N[2.0kgf] | 29.4N[3.0kgf] | 98N[10kgf] | 196N[20kgf] |
| | Moment Stiffness | $2''/\text{N}\cdot\text{cm}$ | $1''/\text{N}\cdot\text{cm}$ | $0.2''/\text{N}\cdot\text{cm}$ | $0.1''/\text{N}\cdot\text{cm}$ |
| | Lost Motion | $<0.050^\circ$ | | | |
| | Backlash | $<0.1^\circ$ | $<0.1^\circ$ | $<0.08^\circ$ | $<0.08^\circ$ |
| | Parallelism | $<50\mu\text{m}$ | $<50\mu\text{m}$ | $<50\mu\text{m}$ | $<50\mu\text{m}$ |
| | Concentricity | $<30\mu\text{m}$ | $<30\mu\text{m}$ | $<30\mu\text{m}$ | $<30\mu\text{m}$ |
| | Wobble | $<0.020\text{mm}$ | $<0.020\text{mm}$ | $<0.020\text{mm}$ | $<0.020\text{mm}$ |
| Sensor | Sensor Part Number | PM-F24(SUNX) | PM-R24(SUNX) | PM-F24(SUNX) | PM-F24(SUNX) |
| | Limit Sensor | Equipped (NORMAL CLOSE) | | | |
| | Origin Sensor | None | | | |
| | Proximity Origin Sensor | None | | | |

| | | | |
|--------|---------------------|---|---|
| Motor | Type | 5-phase stepping motor 0.66A/phase (Tamagawa Seiki Co., Ltd.) | 5-phase stepping motor 0.75A/phase (Oriental Motor Co., Ltd.) |
| | Motor Part Number | TS3664N4(□24) | C9865-90215P(□28) |
| | Step Angle | 0.72° | |
| Sensor | Power Voltage | DC5~24V±10% | |
| | Current Consumption | 15mA or lower | |
| | Control Output | NPN open collector output DC30V or lower, 50mA or lower | |
| | Output Logic | When shaded: Output transistor OFF (no conduction) | |

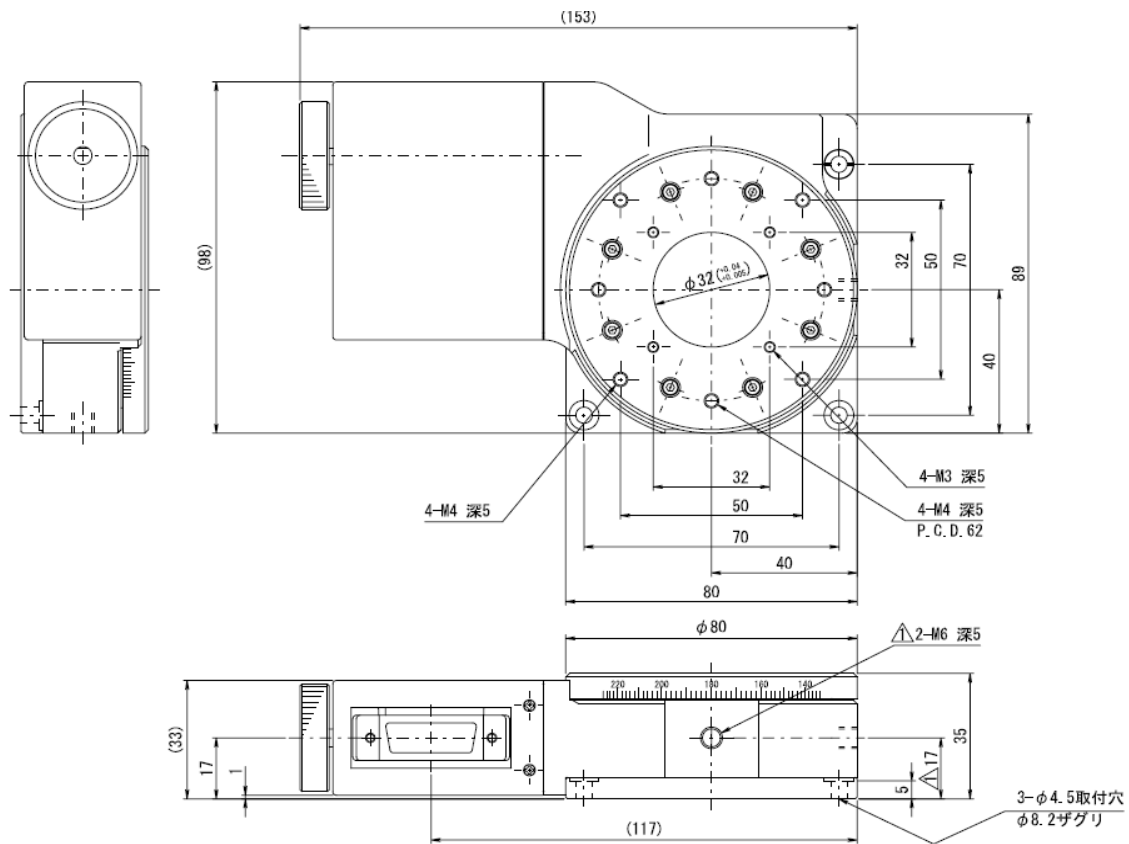
SGSP-40YAW



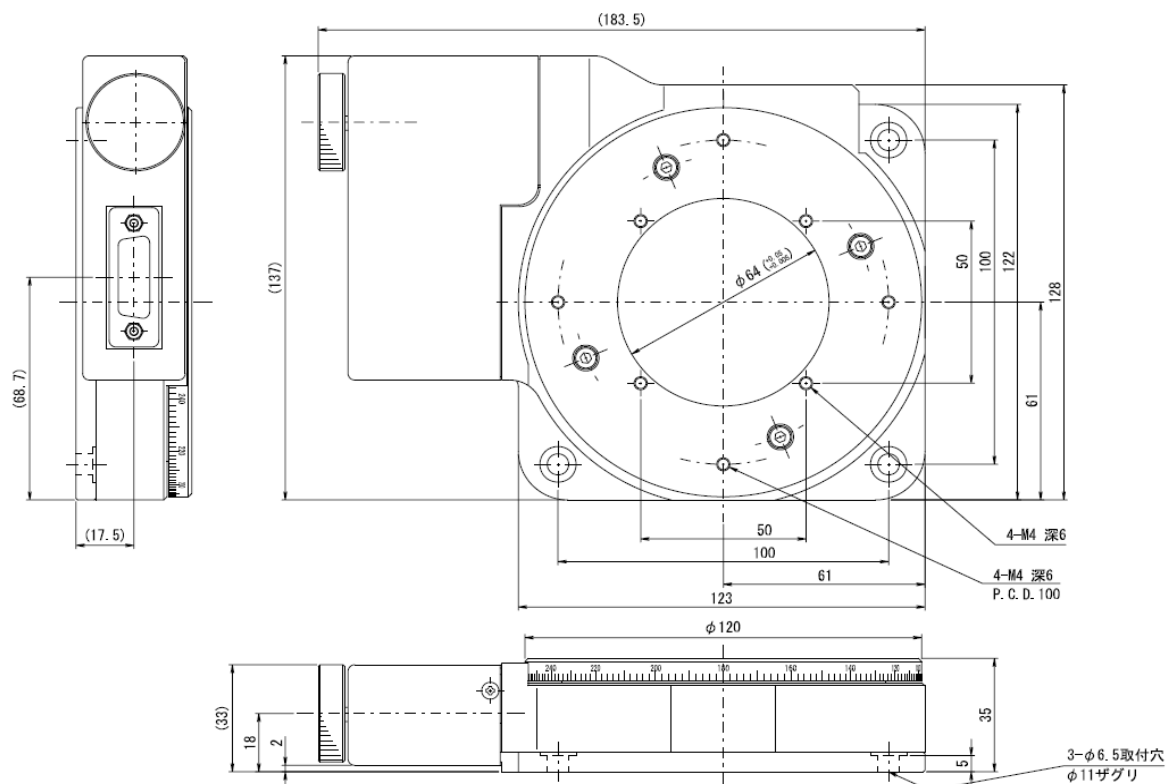
SGSP-60YAW



SGSP-80YAW



SGSP-120YAW



Various Holder

In addition to the following typical lineup, the custom-made of a variety of holders is possible to meet the needs of our customers.

Active System Holder

Fiber Holder



Optical fiber holder for connection to light source or instrument
Two types for LC and SC are available.

Sleeve Chuck Holder



Chucking sleeve and receptacle
Lineup for $\Phi 2\text{mm}$, $\Phi 2.99$ and $\Phi 4.7\text{mm}$.

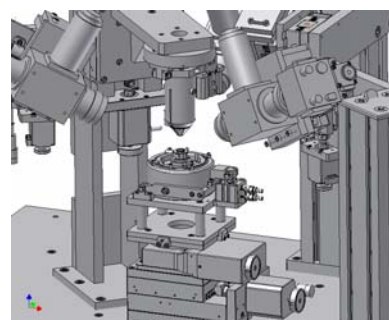
TO Holder



Chucking the device
Lineup for $\Phi 5.6\text{mm}$ and $\Phi 6\text{mm}$.

* Please contact us for other sizes.

* Please contact us for other sizes.



Passive System Holder

Fiber Holder



- Desorption is possible by one touch (magnet)
- By using dedicated positioning unit, the fiber tip and the center of the alignment unit can be fixed.

Fiber Array Holder



- Fixing bare fiber.
- Three types line up by cladding diameter and jacket diameter.
- As needed, outer jacket or Sheath holder can be attached.

Holder with FC Type Connector



- Fixing fiber with FC type connector.
- As needed, outer jacket or Sheath holder can be attached.

Fiber Rotation Holder



- Fixing and rotating the polarization-maintaining fiber.
- Available for jacket diameter of $250\ \mu\text{m}$ and $900\ \mu\text{m}$.

System Applications 1_TOSA/ROSA Assembly Equipment (UV)

- ◆ Automatically aligning the light device and the sleeve with master fiber, and securing to YAG laser welding machine.

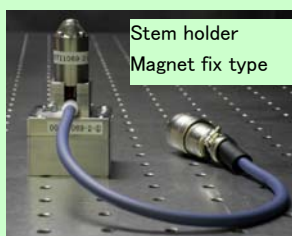


Equipment Overview

- Automatically probing the stem of a user original (PINAMP module) and the optimal alignment position of sleeve with master fiber, and fixing adhesion by irradiating UV light on the UV curable resin portion that was previously applied.
- By matching automatic operation commands (motion, flow control, and alignment), the flow can be newly produced and edited to meet user's specification.
- Stem holder is fixed by magnet and also installed smoothly UV coating unit

Equipment Configuration

- ① 3-axis motorized stage
- ② Stem holder unit
- ③ 3-axis stage driver BOX
- ④ Motion control function Built-in PC Set
- ⑤ Manual operation control BOX
- ⑥ UV coating unit
- ⑦ UV light source
- ⑧ Dispenser unit
- ⑨ Connecting cable

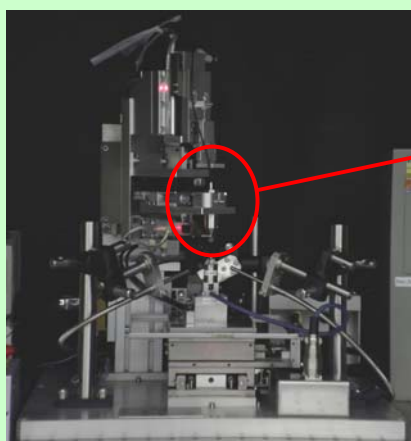


- ① Set the stem, and Installation to UV coating unit

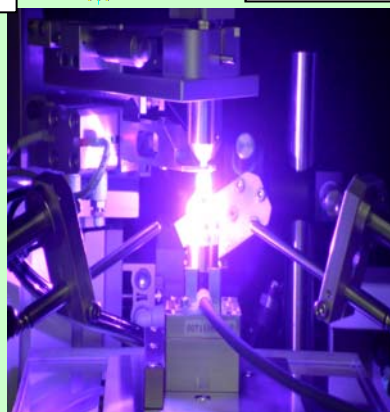
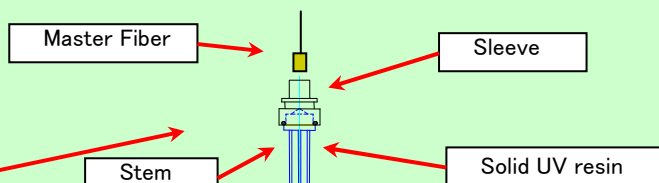


UV coating unit

- ② After applying UV resin Installation to the main



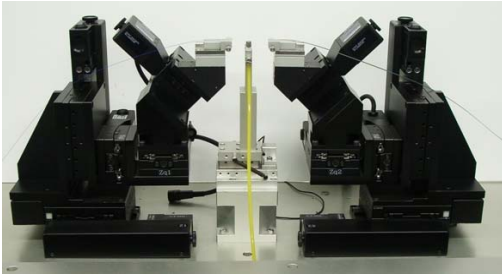
3-axis motorized stage (main unit)



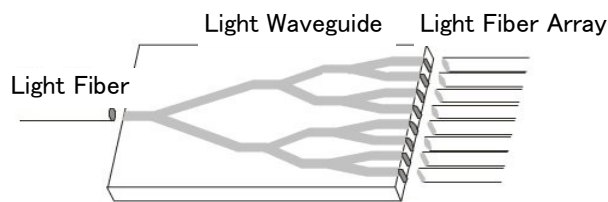
UV irradiation

System Applications 2_ Waveguide Alignment and Evaluation Equipment

- ◆ Equipment for automatically aligning the fiber (array) and the waveguide, and for characteristic evaluation.



- Assembly of the waveguide type devices that require alignment of the incident side and output side, then evaluation.
- By the contact sensor slide way in the middle, can control the gap management of the device or the thickness of the UV-curable resin.
- Effective in the alignment of single core fiber array or of single core fiber, etc.
- By the magnet fixing type, fiber array unit has a good reproducibility and can be detached.



Equipment Configuration

- ① 12 axis motorized stage
- ② 12-axis stage driver BOX
- ③ Motion control function built-in PC set
- ⑤ Contact sensor
- ⑥ Fiber array unit
- ⑦ Connecting cable

System Applications 3_ Fiber Alignment and Evaluation Equipment

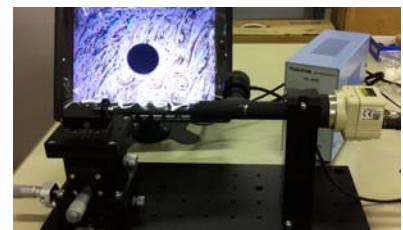
- ◆ An example of an equipment for a special fiber auto alignment and for securing by UV curing adhesive.



- Alignment of Fiber to Fiber, and perform adhesive.
- By the contact sensor slide way, can control the gap management of the device, and perform the adhesive safely.

Equipment Configuration

- ① 6-axis motorized stage
- ② 6-axis stage driver BOX
- ③ Motion control function built-in PC set
- ④ High-definition CCD camera (preset jig)
- ⑤ Contact sensor
- ⑥ Fiber holder unit
- ⑦ Connecting cable



Contact sheet

info@hours-web.com

| | | | | | |
|------------------------------------|--|-----|------|-------|--|
| | | | | Date | |
| Affiliation (Organization Name) | | | | | |
| Department | | | Name | | |
| Country Address | | | | | |
| TEL | | FAX | | Email | |