## HOURS

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PRMS

## Precision Rotation Motorized Stages



### High precision and high stability rotation motorized stages fitted with bearing positioning slide.

Systems Machine

Vision

Application

Manual Positions

**Motion Control** Products

Optical & Mirror Holder

FA Parts

Measurement &Control

**FA Electrical** Parts

Tool & Measure

Cleanroom & AntiStatic

Index

Piezo Stage Precision Linear MS

High Speed MS Motorized Gonimeter

Motorized

Multiaxis

Motorized Industrial Robot

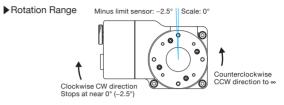
Controller & Driver & Cable

Custom-Built MS



- Rotation motorized stages suitable for when high load capacity is required.
- Back up various inspection instruments according to usage such as the type, size, and measurement range of the measuring object.

#### Guide



- Homing of rotation motorized stages is performed using the CW limit sensor as the origin sensor.
- Origin detection is adjusted so that the stage stops at 0 degree when homing is performed in the MINI system at half step.

#### Attention

- Attention is required when mounting in upside down orientation or on a vertical plane.
- Precision and load capacity specifications may be partly not satisfied depending on the mounting orientation.

Part Number			PRMS-120	PRMS-160
Mechanical Specifications	Rotation Range		Move in the counterclockwise CCW direction to ∞, and stop at near 0 degree (-2.5°) in the clockwise CW direction.	
	Table Size [mm]		φ120	<i>φ</i> 160
	Travel Mechanism (reduction ratio)		Worm gear (1:144)	Worm gear (1:144)
	Positioning Slide		Bearing method	Bearing method
	Stage Material		Aluminum / Aluminum bronze	Aluminum / Aluminum bronze
	Weight [kg]		5	8.5
	Resolution	(Full) [°/pulse]	0.005	0.005
		(Half) [°/pulse]	0.0025	0.0025
	MAX Speed [°/sec]		30	30
	Positioning Accuracy [ ° ]		0.1	0.1
	Positional Repeatability [ ° ]		0.01	0.01
Accuracy	Load Capacity [N]		343 (35.0kgf)	392 (40.0kgf)
Specifications	Moment Stiffness ["/N·cm]		0.015	0.01
	Lost Motion [ ° ]		0.01	0.01
	Backlash [ ° ]		0.003	0.003
	Parallelism [µm]		50	50
	Concentricity [µm]		20	20
	Wobble [mm]		0.01	0.01
Sensor	Sensor Part Number		Micro Photoelectric Sensor: PM-U24 (SUNX Co., Ltd.)	Micro Photo Sensor: PM-R24 (SUNX Co., Ltd.)
	Limit Sensor		Equipped (NORMAL CLOSE)	Equipped (NORMAL CLOSE)
	Origin Sensor		None	None
	Proximity Origin Sensor		None	None

Motor / Sensor Specifications						
Motor	Туре	5-phase stepping motor 1.4A/phase (Tamagawa Seiki Co., Ltd.)				
	Motor Part Number	TS3624N42E (□60mm)				
	Step Angle	0.72°				
Sensor	Power Voltage	DC5 - 24V ±10%				
	Current Consumption	15mA or lower				
	Control Output	NPN open collector output DC30V or lower, 50mA or lower				
	Output Logic	When shaded: Output transistor OFF				

Compatible Driver / Controller						
Control System	Compatible Driver	SD-5M, SD-55M, SD-514MSC, SD-5151, SD-525M				
	Compatible Controller	ASC-302GS, ASC-304GS				

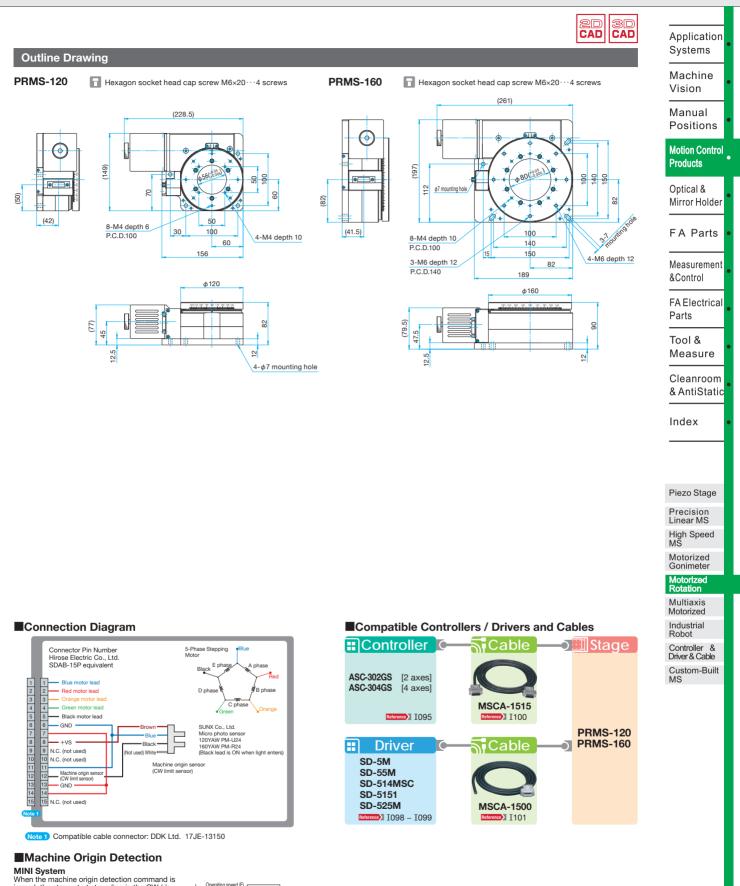
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**RoHS** CE

PRMS



When the machine origin detection command is issued, the stage starts traveling in the CW (-) direction at the operating speed (F) set with the memory switch, and stops by the CW (-) side limit sensor. Then it travels in the CCW (+) direction at the operating speed (F) for 1000 nulses pulses. After stop, it starts traveling in the CW (-)

After stop, it starts traveling in the CW (-) direction again at the starting speed (S), and stops by the CW (-) side limit sensor. After that, it travels in the CCW (+) direction at the operating speed (F) for 1000 pulses. This position is regarded as the machine origin.

Operating speed (F) Stage CW (-) erating speed (F) 1000 pulse trave > 0p CCW (+) - Starting speed (S) CW (\_) Operating speed (F) 1000 pulse travel CCŴ (+)

CW (-) side limit sensor